





Tera Scale Systems and Applications

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NASA's Computational Challenges



– Aeronautics

- X-Vehicle Development
- Shuttle Upgrades
- Airspace Control and Simulation
- Astrobiology
 - Protein Folding and Beyond
- Earth Science
 - Atmospheric Physics
 - Oceanography
- Nano Technology
 - Chemistry
- Space Science
 - Stellar Dynamics
 - Chemistry/Spectra
 - Instrument Data Analysis and Support
 - Planetary Modeling



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2760	Origin CPUs			
 28	Subtotal			
 4	O2k	That	Storage	
4	O2k	This	Storage	
8	O2k	Lou2	Storage	
12	O2k	Lou	Storage	
1184	Subtotal			
8	O2k	Fermi	Production	
24	O2k	Turing	Production	
64	O2k	Sunrise	Production	
64	O2k	Kalney	Production	
64	O2k	Jimpf1	Production	
64	O2k	Jimpf0	Production	
64	O2k	Dixon0	Production	
64	O2k	Hopper	Production	
256	O2k	Steger	Production	
512	O2k	Lomax2	Production	
1548	Subtotal			
4	O2k	Piglet	Development	
8	O2k	Evelyn	Development	
1024	O3k	Chapman	Development	
512	O2k	Lomax	Development	
#CPUs	System	Name		
Current SGI Inventory - ~ 20 systems				



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-standing stands to the standing of

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Goal: Production Quality Highly Parallel Supercomputer



- What is a Production Supercomputer?
 - Significantly faster that previous generation
 - Less Expensive
 - Productive Environment for the Users (easy to use)
 - As reliable as the "Gold Standard"
- Have to move into the realm of hundreds or thousands of processors
 - Its all about the interconnect
- Many Attempts (these all failed...)
 - Connection Machines CM2 (performance)
 - Connection Machines CM5 (performance)
 - Intel IPSC-860 (performance)
 - Intel Paragon (performance)
 - IBM SP2 (performance)
 - SGI Power Challenge Cluster (reliability)
 - Cray J90 Cluster (vendor backed out of commitment)

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- There are many problems that require supercomputing
- However, its typical that applications may require substantial modifications to achieve even moderate levels of parallelism.
- This can translate into several man years of effort, and when you have done this, you'll likely not run faster that a C90 supercomputer manufactured in 1993.
- Many (most) productive scientists are simply unable to access supercomputing because it either difficult or even not possible to effectively scale their applications.
- For example,
 - Computational Chemistry
 - DAO
 - Molecular Dynamics
 - Space Science

Shared memory can go a long way towards SIMPLIFICATION.

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Are we getting sustained performance on parallel systems for our real applications?



FVCORE 2x2.5@55 Levels (B55)





Are we getting sustained performance on parallel systems for our real applications?



FVCORE 1x1.25@55 Levels (C55)





Performance (mostly from 1996)



ARC3D



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256p Origin2000





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512p Origin2000





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Lomax: 512 Processor Origin2000





Xtreme ccNUMA

Cost/performance OVERFLOW-MLP

- Cost/perf O2K/C90 = 37.7x
- Cost/perf O2K512 to O2K256 = 1.6x
- Performance over 256p = 3x
- Performance over C90/16 = 13x

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CPUs

512 MIPS R12000 300 MHz CPUs 600 MFLOP/s per CPU Peak 307 GFLOPS total (19 x C90) Peak 8 MByte cache per CPU (4 GByte total) Memory 192 GB main memory (24 x C90) *Hypercube interconnect* (9 hops) Disk 2 TB FC Raid disk subsystem System Software

Develop OS true single system image

Single XFS File System

Compiler parallel loops 512 CPUs wide

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256p Single System Image





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NUMA Aware Operating System







NUMA Aware Operating System









- Dynamic management of CPUSETs
 - CPUSET created of size N at job start
 - CPUSET deleted at job termination

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Single CPU





SpecFP 2000 harmonic mean of base ratios



SpecFP2000 Throughput



SpecFP 2000 Throughput









Shared Memory Multi-level Parallelism (MLP) is the utilization of multiple levels of parallelism within an application executing on a NUMA based system architecture in order to increase its parallel efficiency during execution. It is an open system design and has the following attributes:

- Usually two levels of parallelism
- Coarse grained parallelism provided by Unix forked processes
- Fine grained parallelism provided by the compiler at loop level
- No messaging communication by Unix shared memory arenas
- Targeted for the new large CPU count NUMA SMP systems
- Method can also execute across clusters





The diagram below is a graphical description of how user common blocks are mapped onto the system. In essence each virtual SMP executes a single a.out. Any data the user wants to share across a.out's is declared in the shared memory arena, and essentially appears as a common variable seen by all.





MLPlib



The MLPlib routines for scalable parallel execution support are:

- <u>Subroutine GETMEM(xarray,xpoint,numxbyt)</u>
 - The GETMEM routine allocates numxbyt bytes to the xarray variable
 - resident in the shared memory arena. The xarray data will be visible to all
 - *MLP* processes using the shared memory arena.
- <u>Subroutine FORKIT(nthread,numpro,nowpro)</u>
 - The FORKIT routine spawns a total of numpro processes for the job
 - including the current one in the total. Nowpro is returned, and is the
 - current process id (1-numpro).
 - Nthread is an array of ints, indicating the number of OMP threads for each MLP process
- Subroutine BARRIER(numpro)
 - The BARRIER routine waits until numpro processes have hit the
 - barrier, then all drop through.

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Forkit.f



С* Fork the Processes * nowpro=1 c----count offsets to starting cpus ival=0 do n=1,numpro write(*,520) n istart(n) = ival ival=ival+nthread(n) enddo c----spawn the threads - manual forks do n=2,numpro nowpid=getpid() if(nowpid.eq.master) then ierror=fork() endif nowpid=getpid() if(nowpid.ne.master) then nowpro=n go to 200 endif enddo

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c----create mp environment
200 call omp_set_num_threads(nthread(nowpro))

c----check for pin request call getenv('PIN_TO_CPUS',evalue) if(evalue.ne.'') then read(evalue,*) idopin endif if(evalue.eq.'') then idopin=0 endif if(idopin.eq.0) return

!\$omp parallel
 call mp_assign_to_cpu3(omp_get_thread_num(), istart(nowpro))
!\$omp end parallel

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Figure out which physical cpus you have access to pmoctl(PMO_GETNODEMASK_UINT64,&sys_nodemask,sizeof(sys_nodemask)) req.request = CPUSET_QUERY_CPUS; sysmp(MP_CPUSET, &req)

Figure out which physical memory the cpu is attached to

sysmp(MP_NUMA_GETCPUNODEMAP,

(void *)cpu_node_mapping, sizeof(cnodeid_t) * ncpus)

Demand physical pages be allocated from the memory attached to the CPU you will assign to this thread.

mld_create(1,1024) mldset_create(&mld, 1) mldset_place(mldset, TOPOLOGY_PHYSNODES, &affinity_info, 1, RQMODE_MANDATORY);

Locks the thread that called this routine to the chosen physical cpu

sysmp(MP_MUSTRUN, cpulist[my_rank+starting_point])

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INS3D Objectives



Enhance incompressible flow simulation capability for developing aerospace vehicle components, especially, unsteady flow phenomena associated with high speed turbo pump.





Space Shuttle Main Engine Redesign





- External Tank filled with approx. 2 Olympic size pools worth of Liquid Hydrogen and Oxygen.
- Main engine turbo pump pushes 1 Olympic size pool every two minutes.
- If water were pumped it would produce a fountain 12 miles high.
- Redesign to reduce approx 1000 lbs of engine weight and increase engine efficiency.
- Will result in a significant payload capacity increase.

(Fact – First Shuttle Launch

April 12, 1981, 7:00:03 a.m. EST)

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Validation (SSME Impeller)





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SSME Upgrade - RIG1





- Full analysis 3-5 rotations of the pump.
 - Takes about a year on a Y-MP
 - Currenly about a week on 80 CPUs of Origin3000
 - performance goal 1 day
- After about 2 weeks on 160 Origin 3000 CPUs, got it to turn 40 degrees!

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SSME-rig1 / Initial start



TIME STEP 5





SSME-rig1 / Initial start



TIME STEP 7 / Impeller rotated 3-degrees at 30% of design speed





INS3D Parallelization



INS3D-MLP / 40 Groups

RLV 2nd Gen Turbo pump 114 Zones / 34.3 M grid points



Per processor Mflop is between 60-70. This is a vector code.

Code optimization for cache based platforms is currently underway. Target Mflops is to reach 120 per processor. Increasing number of OpenMP threads is also the main objective for this effort.

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INS3D Shuttle Main Engine Upgrade 34.3 Million Points/114 Zones 40 MLP Groups Pin vs. No Pin SN0 400mhz Pin -SN1 400mhz No Pin -SN1 400mhz Pin Seconds/Itteration 0 -#CPUs NASA CUG 2001 - Bob



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INS3D Shuttle Main Engine Upgrade 34.3 Million Points/114 Zones 40 MLP Groups Pin vs. No Pin SN0 400mhz Pin SN1 400mhz No Pin SN1 400mhz Pin Perfect Speedup Seconds/Itteration 0 -#CPUs NASA CUG 2001 - Bob



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c----check for pin request call getenv('PIN_TO_CPUS',evalue) if(evalue.ne.'') then read(evalue,*) idopin endif if(evalue.eq.'') then idopin=0 endif if(idopin.eq.0) return

!\$omp parallel

call mp_assign_to_cpu3(omp_get_thread_num(), istart(nowpro)) \$ somp end parallel

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INS3D - Speedups Pin vs No Pin







This case is a simulation of a full aircraft configured for landing. It is a 35 million point problem distributed across 160 grids of widely varying size. The problem is interesting for several reasons. They are:

- It is one of the largest problems ever solved at NAS
- It requires hundreds of dedicated C90 CPU hours per run
- It fully stress tests the MLP code for correctness and performance
 - Load balance is a major issue with this problem
 - Cache issues are important (some grids break cache)
- It fully tests the Origin system hardware and software components
- The Overflow code is widely used within and outside of NASA

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Overflow - Transport Configured for Landing 32 Million Points/150 zones No Pin vs Pin (03000)









Overflow - Transport Configured for Landing 32 Million Points/150 zones

No Pin vs Pin (O3000)









Overflow - Transport Configured for Landing 32 Million Points/150 zones No Pin vs Pin (03000)

















- 2 operational 512p 400mhz O3000 system
 - testing and fallout
 - staff and small group of users on systems
- Plan to bring up 1024p in initial topology configuration in June
- Move to higher bandwidth/lower latency topology by end of summer
- Processor speed upgrade around year end +-
- Expectation is to sustain 20% of peak 240 Gflops

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Some Open Issues



- Page placement doesn't always work as expected
 - some (not all) pages allocated via the mld scheme do not end up on the designated node
- Some nodes do not de-allocate memory fully when a job exits, forcing future jobs to allocate memory off other nodes.
- MId_create returns a EINVAL with static parameters
- Sporadic issues with responsiveness possibly related to I/O activity
- CPU X not seen for 20 seconds. Process sleeping at SPL high.



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