
Evaluation of UPC on the Cray X1E

Cray User Group 2006, Lugano, Switzerland
May 10, 2006

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“Evaluation of UPC on the Cray X1”

Tarek A. El-Ghazawi, François Cantonnet, Yiyi Yao, and Jeffrey Vetter

Since then,

1.X1@ORNL => X1E

2.NPB-UPC: pragmas inserted.

X1E at ORNL: Phoenix

- ➔ 1024 Multi-streaming vector processors (MSP)
- ➔ Each MSP
 - 4 Single Streaming Processors (SSP)
 - 4 scalar processors (400 MHz)
 - Memory bw is roughly half cache bw.
 - 2 MB cache
 - 18 GFLOP peak (~18.5 TFLOPS)
- ➔ 4 MSPs form a node
 - 8 GB of shared memory.
 - Inter-node load/store across network. 56 cabinets



Memory Latency

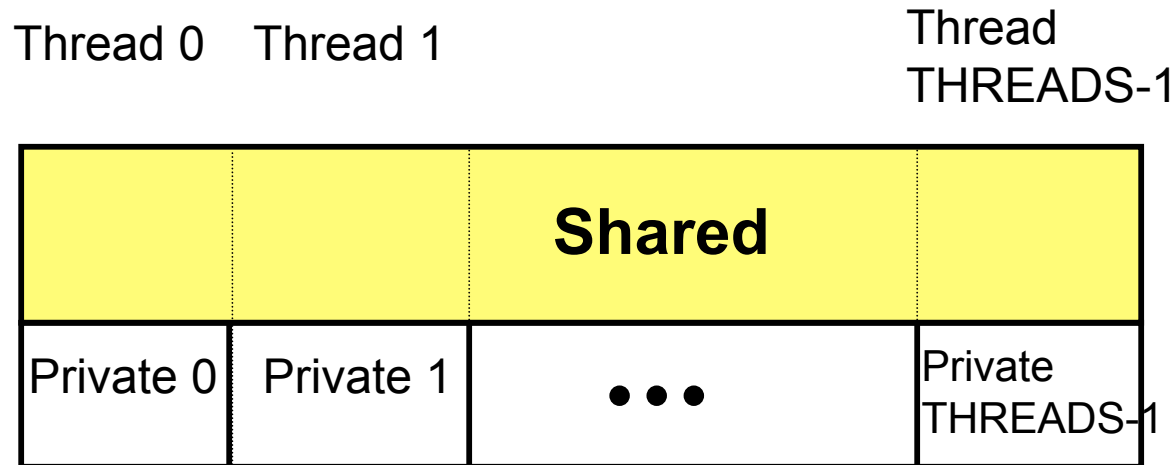
<i>Memory location</i>	<i>Relative access time</i>
D-cache	1X
E-cache	2X
Local (node) memory	7X
Remote (off node) memory	10X-32X

A Brief History of UPC

- ➔ Extension of ISO C
- ➔ Partitioned global address space language. (PGAS)
 - DSM programming model
 - SPMD execution model
- ➔ May 1999: Initial specification.
 - Tech report: *Carlson, Draper, Culler, Yellick, Brooks, and Warren.*
- ➔ May 2000: First UPC Consortium Meeting.
- ➔ Feb 2001: Spec v1.0
- ➔ Dec 2003: UPC Collectives spec.
- ➔ July 2004: UPC I/O spec.
- ➔ May 2005: v1.2
- ➔ Sept 2005: First PGAS meeting in Minneapolis.

UPC Memory Model

Global address space



- ➔ **A pointer-to-shared can reference all locations in the shared space, but there is data-thread **affinity****

UPC Execution Model

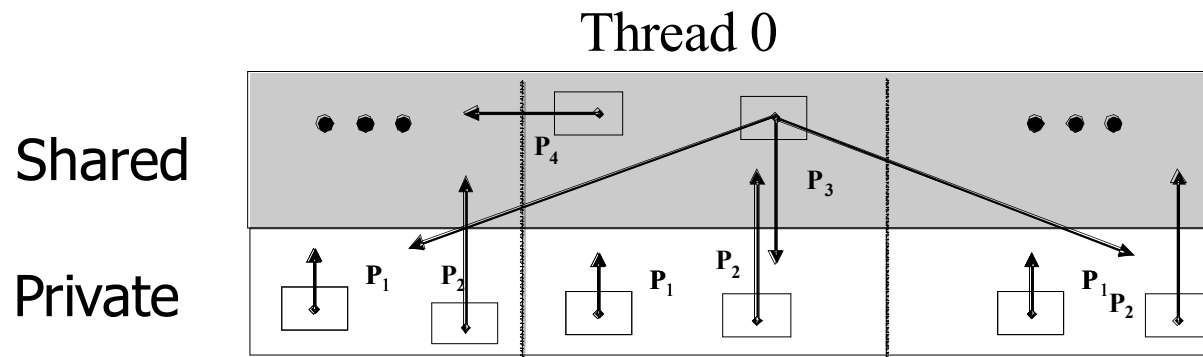
- ➔ A number of threads working independently in a SPMD fashion
 - MYTHREAD specifies thread index (0..THREADS-1)
 - Number of threads specified at compile-time or run-time

- ➔ Synchronization when needed:
 - Barriers
 - Locks
 - Memory consistency control

➔ How to declare them?

```
int *p1;           /* private pointer pointing locally */
shared int *p2;   /* private ptr pointing into the shared space */
shared int *shared p3; /* shared ptr pointing into the shared space */
```

➔ You may find many using “shared pointer” to mean a pointer pointing to a shared object, e.g. equivalent to p2 but could be p3 as well.



Memory Consistency Models

- ➔ Has to do with ordering of shared operations, and when a change of a shared object by a thread becomes visible to others
 - Relaxed consistency: shared operations can be reordered by the compiler / runtime system
 - Strict consistency: enforces sequential ordering of shared operations. (No operation on shared can begin before the previous ones are done, and changes become visible immediately)

Memory Consistency Models

-
- ➔ User specifies the memory model through:
 - declarations
 - pragmas for a particular statement or sequence of statements
 - use of barriers, and global operations

 - ➔ Programmers responsible for using correct consistency model



The NAS Parallel Benchmarks (NPB)



- ➔ Evolved from NASA applications (CFD)
- ➔ Strong scaling.
- ➔ Now MPI, OpenMP, HPF, Co-array Fortran, UPC, Java, Grid,...

<http://www.nas.nasa.gov/Software/NPB/>

NPB problem sizes (Classes)

```
if (class == 'S')
    problem_size = 12; dt = "0.015"; niter = 100;
else if (class == 'W')
    problem_size = 36; dt = "0.0015"; niter = 400;
else if (class == 'A')
    problem_size = 64; dt = "0.0015"; niter = 400;
else if (class == 'B')
    problem_size = 102; dt = "0.001"; niter = 400;
else if (class == 'C')
    problem_size = 162; dt = "0.00067"; niter = 400;
```

UPC version of NPB

- Modified from NPB2.4-MPI and NPB2.4-OMP
 - *F. Cantonnet, Y. Yao, and T. El-Ghazawi*
- *upc_forall, upc_barrier, upc_notify_wait, upc_lock, upc_memput, upc_memget, upc_reduce_sum*
- *Relaxed mode*
- *Future plans: Reduce reliance on global barrier using fence, organization, etc.*

Conjugate Gradient (CG)

- Computes an approximation to the *smallest eigenvalue* of an spd matrix.
- Unstructured grid computations requiring *irregular long-range communications*.

Loopmarking listing file (MG)

Before Pragmas

```
1155. 1 2 r-----<   for ( i1 = d1; i1 <= mm1-1; i1++)
1156. 1 2 r           {
1157. 1 2 r           u((2*i3-d3-1), (2*i2-d2-1), (2*i1-d1-1)) =
1158. 1 2 r             u((2*i3-d3-1), (2*i2-d2-1), (2*i1-d1-1))
1159. 1 2 r             +z((i3-1), (i2-1), (i1-1));
1160. 1 2 r----->   }
```

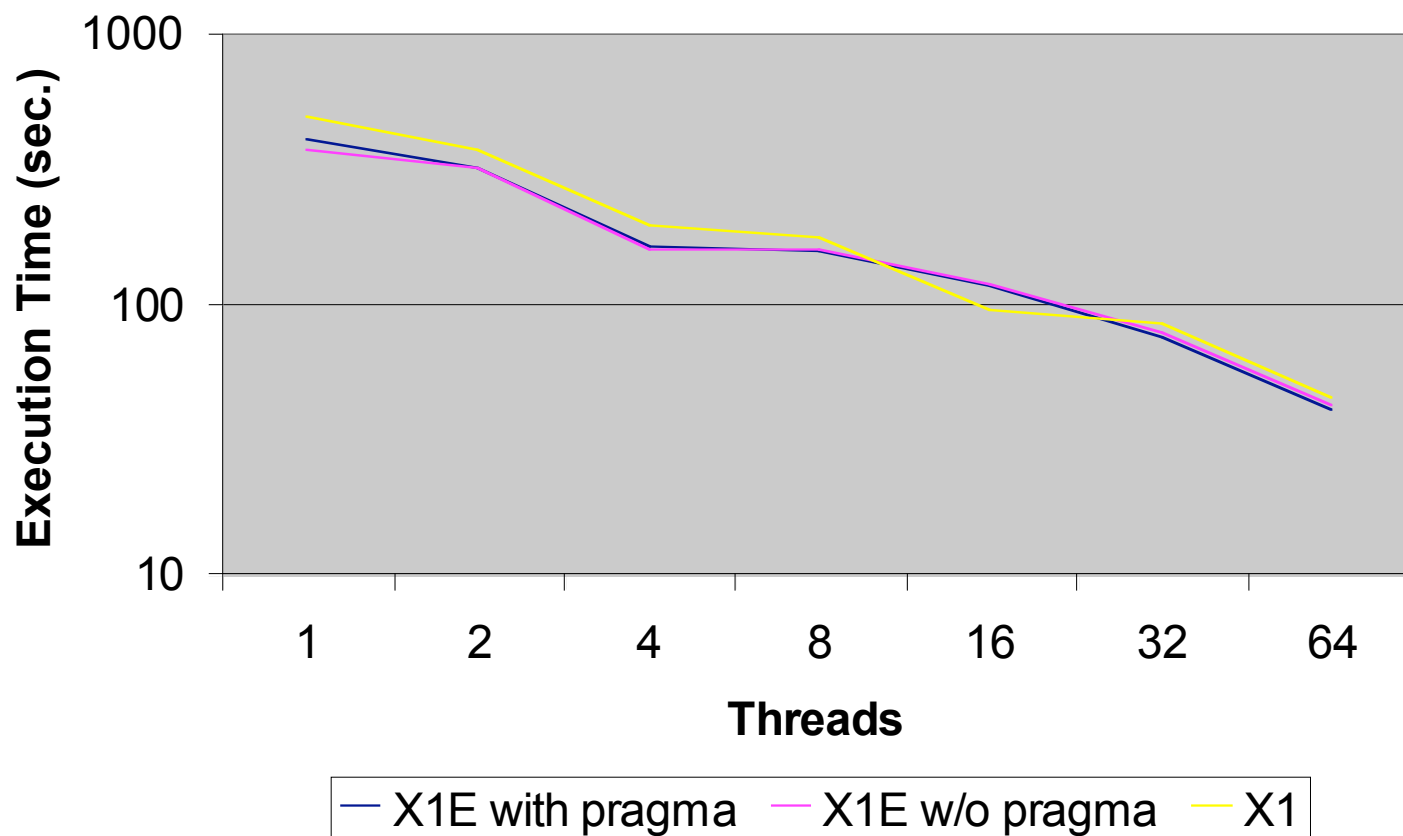
Loopmark listing file (MG)

Pragmas

```
1155. m 2      #pragma _CRI concurrent
1156. m 2      #pragma _CRI ivdep
1157. m 2 MV---<   for ( i1 = d1; i1 <= mm1-1; i1++)
1158. m 2 MV      {
1159. m 2 MV          u((2*i3-d3-1), (2*i2-d2-1), (2*i1-d1-1)) =
1160. m 2 MV          u((2*i3-d3-1), (2*i2-d2-1), (2*i1-d1-1))
1161. m 2 MV          +z((i3-1), (i2-1), (i1-1));
1162. m 2 MV--->   }
```


CG Performance

CG Class B

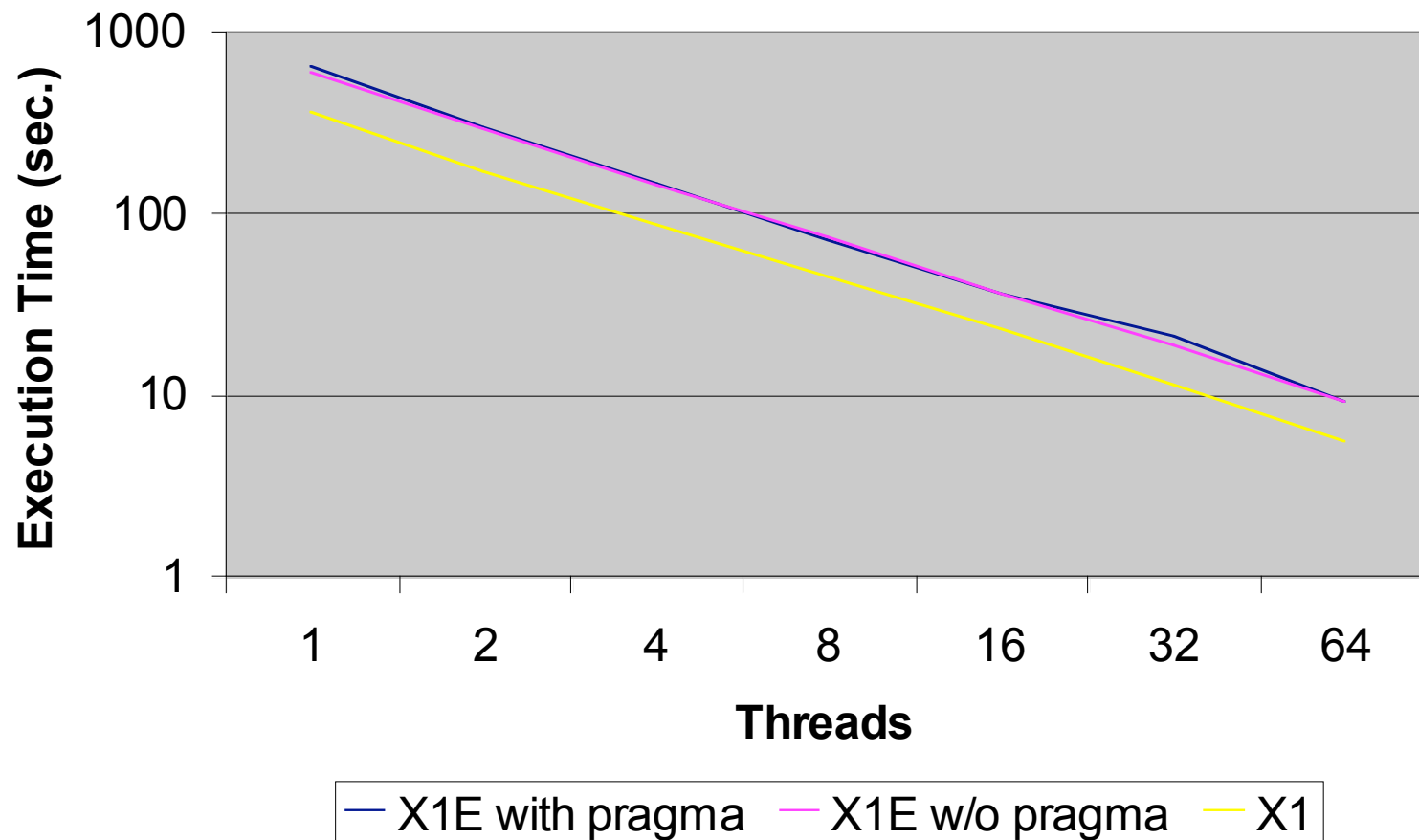


Monte Carlo “Pleasantly” Parallel (EP)

- ➔ *Compute independent Gaussian deviates with $\mu = 0$ and $\sigma^2 = 1$.*
- ➔ Only communication is a summation of ten values at the end of execution.

EP Performance

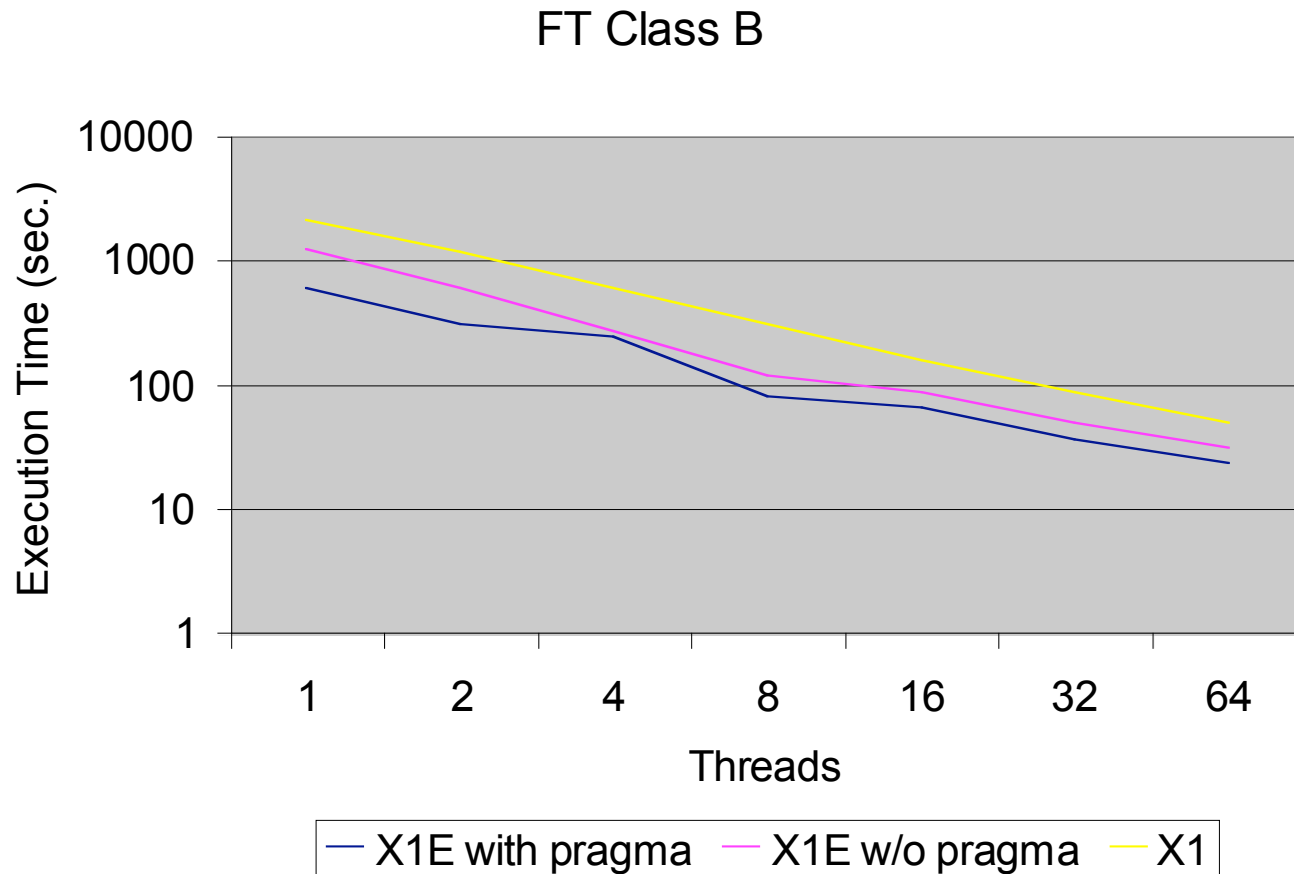
EP Class B



Fourier Transform (FT)

- Solves a 3D partial differential equation using an *FFT-based spectral method*, also requiring long range communication.
- FT performs three 1-D FFT's, one for each dimension.

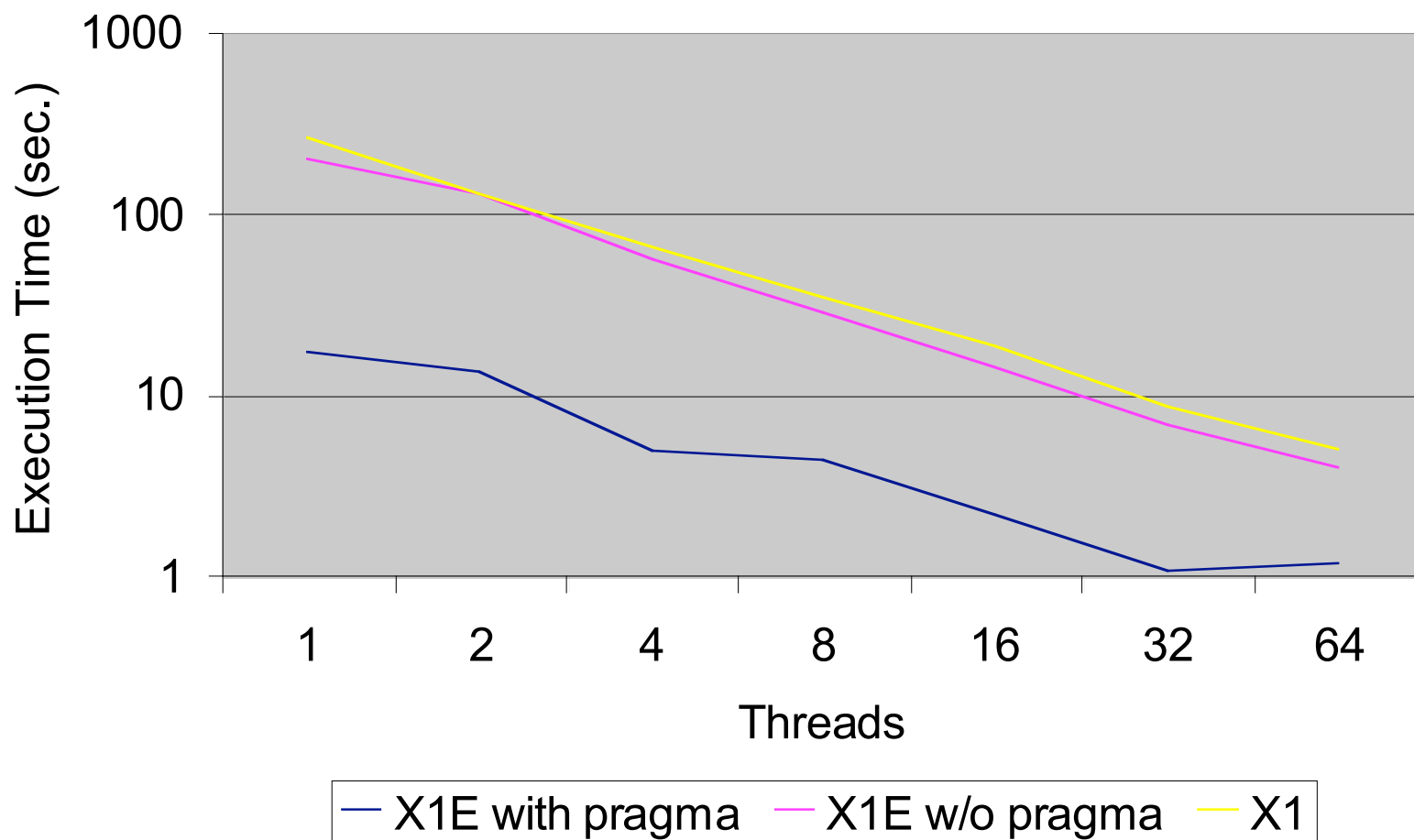
FT Performance



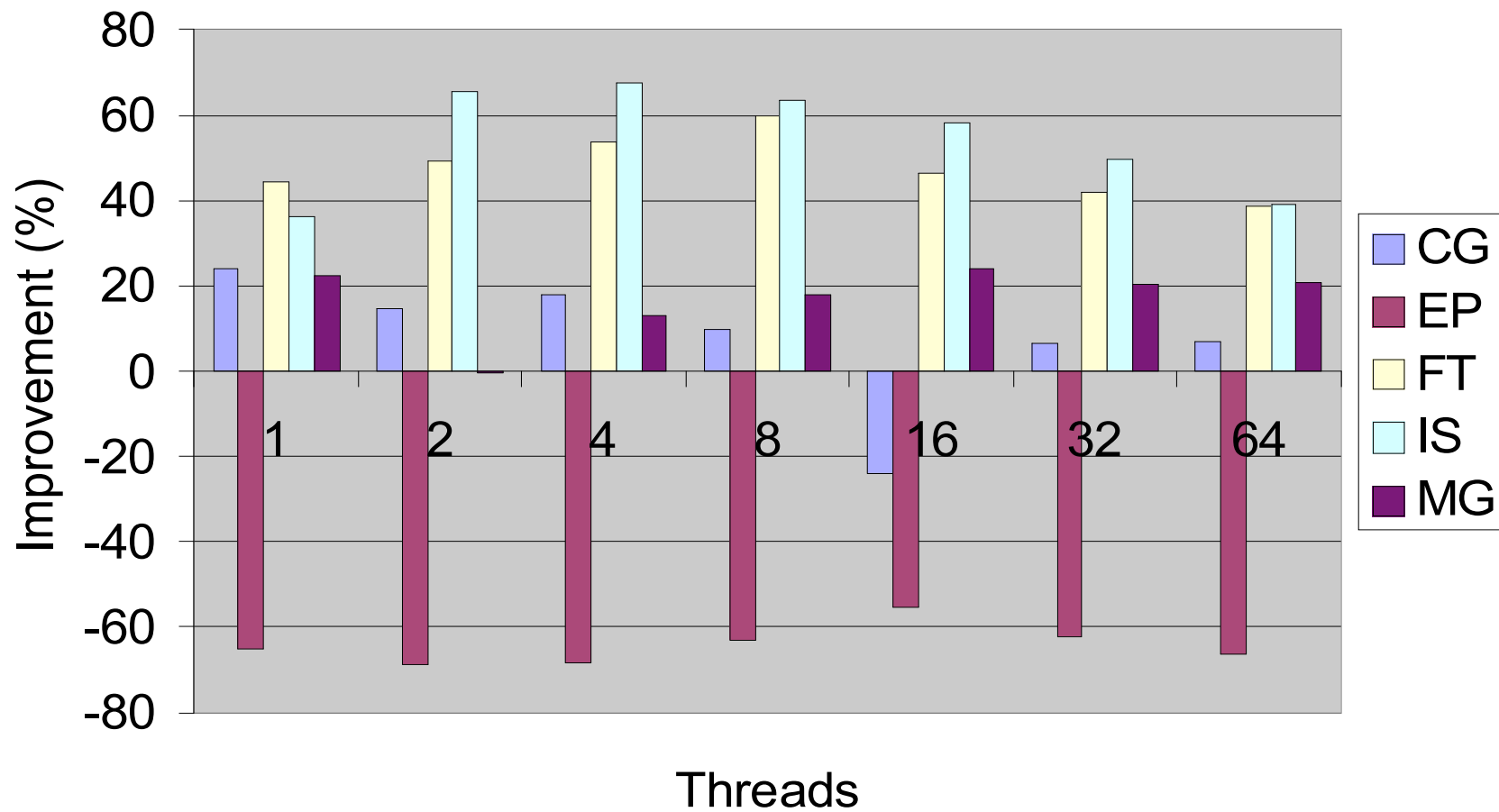
MG: Multi-grid

- uses a V-cycle multi-grid method to compute the solution of the 3-D scalar Poisson equation
- requiring both short and long-range highly structured inter-process communication.

MG Class B



X1E / X1 improvment



Summary

- X1E has a positive effect on performance for some (FT, MG), little effect for others (CG), and a negative effect for one (EP).
- Guided by loopmark listing, careful insertion of pragmas can have a significant effect.



Acknowledgements



- ➔ This research was sponsored by the Office of Mathematical, Information, and Computational Sciences, Office of Science, U.S. Department of Energy under Contract No. DE-AC05-00OR22725 with UT-Battelle, LLC. Accordingly, the U.S. Government retains a non-exclusive, royalty-free license to publish or reproduce the published form of this contribution, or allow others to do so, for U.S. Government purposes.
- ➔ Cray, esp. Cathy Willis.

PGAS 2006

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- ➔ October 3-4, Washington, DC (GWU)
 - ➔ CFP coming soon. (Paper submissions)
 - ➔ UPC Developers workshop
 - ➔ CAF Developers workshop