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Domain Decomposition Performance on ELMFIRE Plasma Simulation Code

F. Ogando^{1,3}, J. Heikkinen², S. Janhunen³,
T. Kiviniemi³, S. Leerink³, M. Nora³

1) UNED, Spain

2) VTT - EURATOM Tekes, Finland

3) TKK - EURATOM Tekes, Finland

Supporting CUG site
CSC



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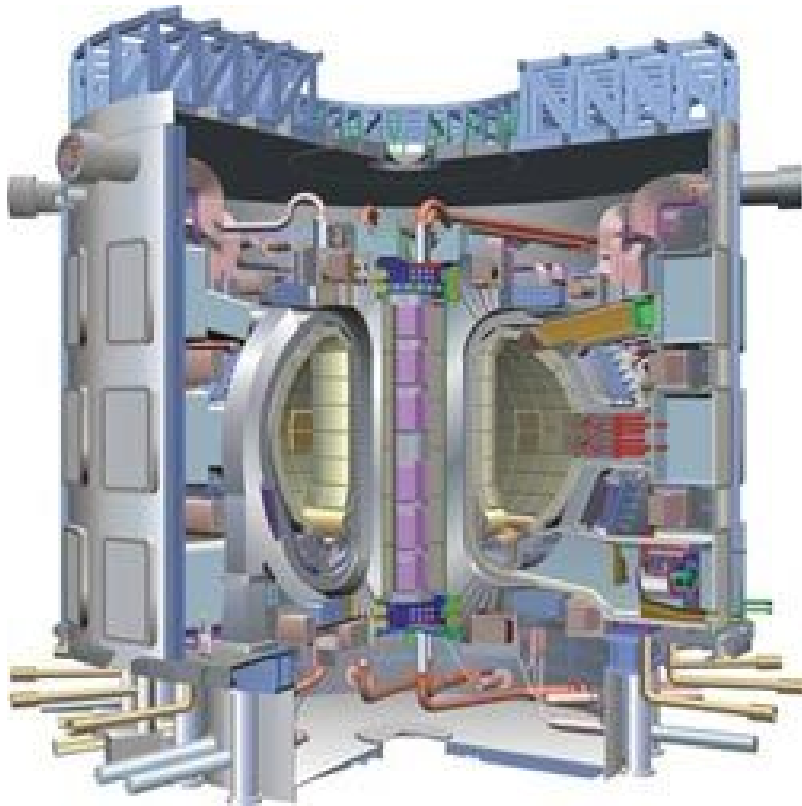
Outline

- Nuclear fusion and plasma physics
- ELMFIRE simulation code
 - Some physics inside
 - Matricial problem
- Domain decomposition
 - New topology
 - Results



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Nuclear Fusion: The energy of the stars



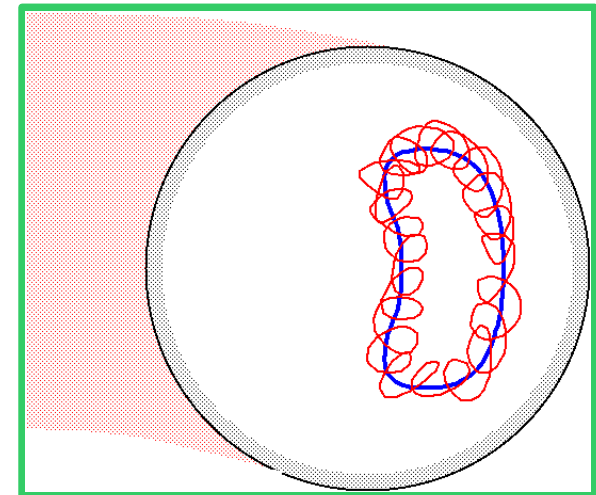
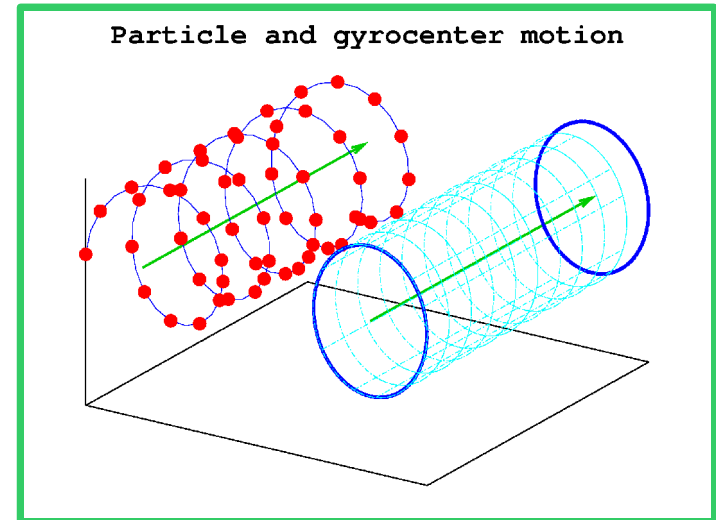
- EU is a main supporter and host of ITER, the biggest civilian fusion reactor ever.
- Keeping a hot reacting plasma confined still poses scientific and technological problems.



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Gyrokinetic model for plasmas

- Plasma particles follow field lines with highly oscillating helicoidal movement.
- However their gyration centers follow smoother lines close to B-lines.
- Gyrokinetic model deals with particle gyrocenters, which present smoother transversal trajectories.



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Crossing the Boundaries



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The ELMFIRE group



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Founded in 2000

International group

Finland

Spain

Netherlands

Main affiliations

VTT

TKK

... but also ...

CSC

Åbo Akademi

UNED (Spain)



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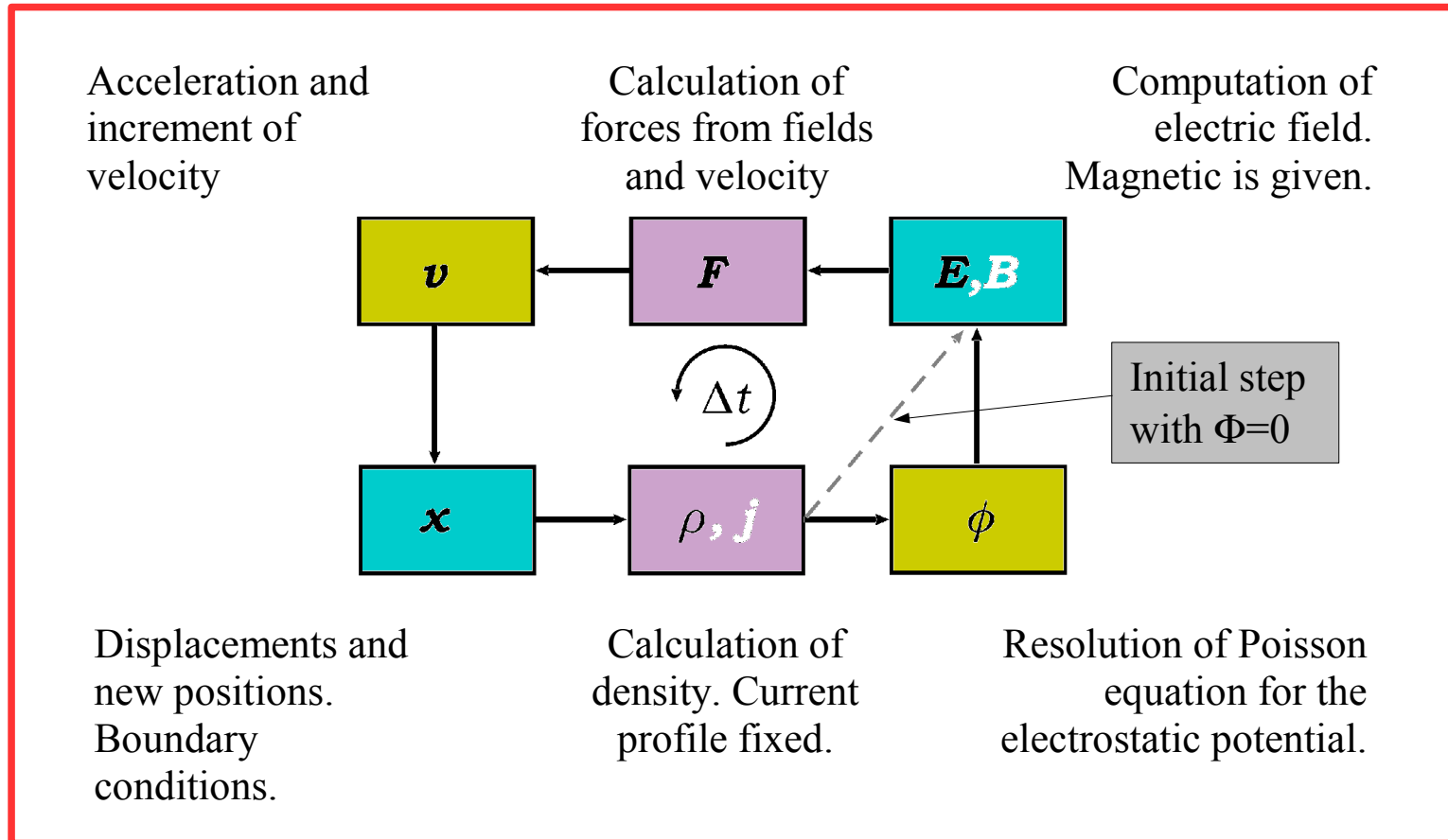
ELMFIRE code

- Full-f nonlinear gyrokinetic particle-in-cell approach for global plasma simulation.
- Parallelized using MPI with very good scalability.
 - Based on free and optionally proprietary software: PETSc, GSL or PESSL, ACML, MKL ...
- Benchmarked against other gyrokinetic codes.



Calculation flux in ELMFIRE

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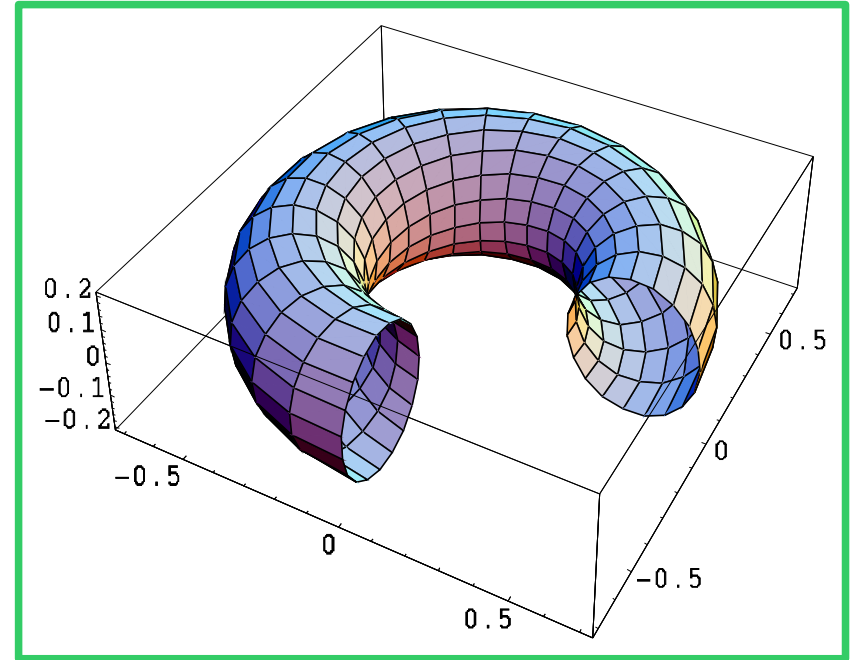




Poisson equation

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- Particles move in a electrostatic field.
- Field is calculated on a field-aligned 3D mesh.
 - Lines are twisted along the azimuthal direction.



$$\nabla^2 \Phi + \frac{q^2}{mB\epsilon_0} \int \left[(\Phi - \langle \Phi \rangle) \frac{\partial \langle f \rangle}{\partial \mu} + \frac{m}{q\Omega} \langle f \rangle \nabla_{\perp}^2 \langle \Phi \rangle \right] dv = -\frac{1}{\epsilon_0} (q\tilde{n}_i(\vec{r}) - en_e(\vec{r}))$$



ELMFIRE requirements

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- ELMFIRE is has excellent parallelization in most tasks. Particles are splitted among processors.
- CPU-time (T) is directly related to the number of markers being treated in a single processor (N_P/P).
- Memory usage (M) is proportional to the size of grid (G), since it is not properly splitted among processors.
- The number of particles per cell lies in certain limits.

$$T \propto \frac{N_P}{P}; \quad M \propto G; \quad N_P \propto G \quad \rightarrow \quad M \propto P \cdot T$$



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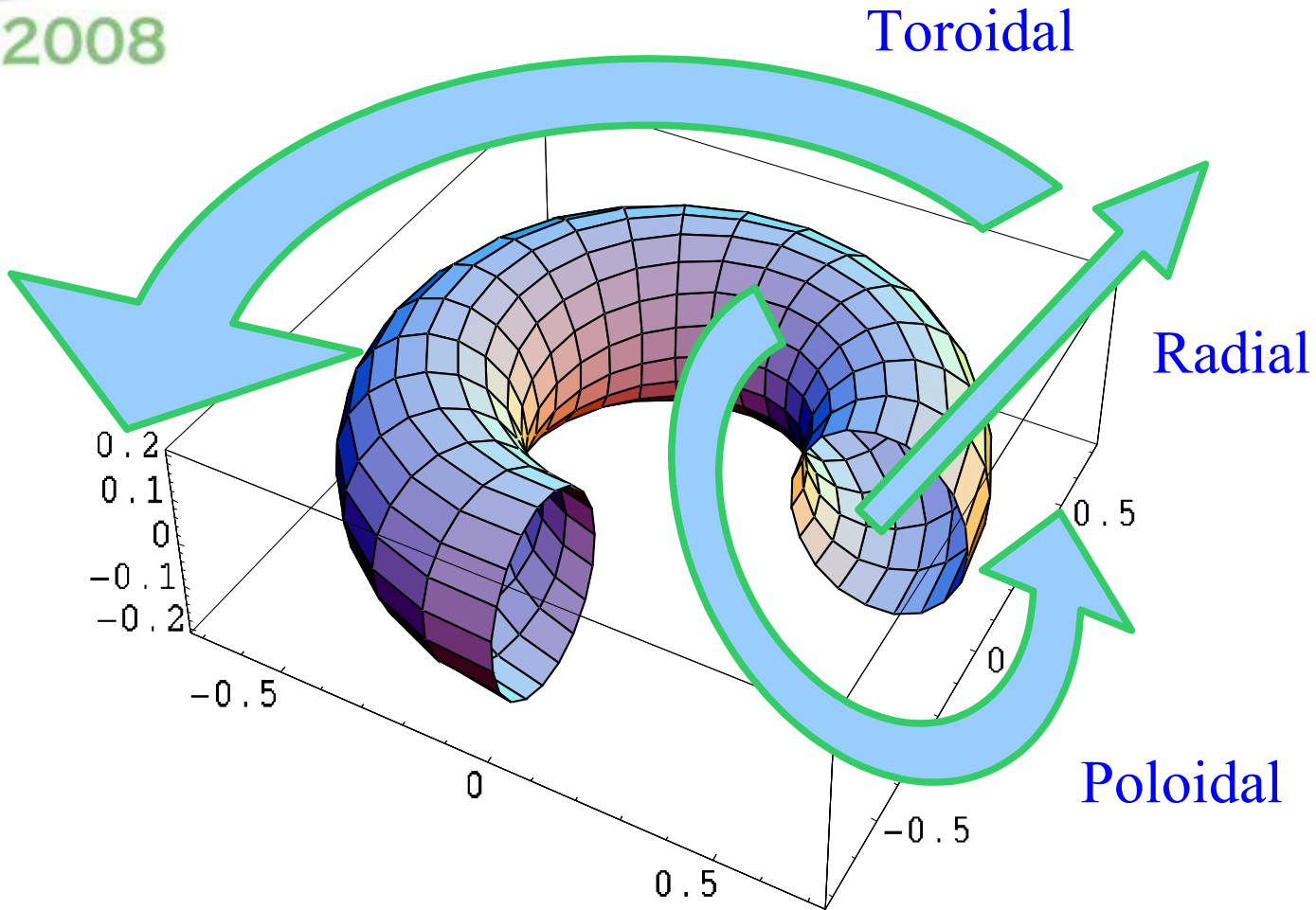
GK-Poisson problem in ELMFIRE

- The code computes electrostatic field so that the calculated trajectories keep the plasma neutral
- The most sensitive part of the dynamics is computed implicitly
 - Future potential changes trajectories, which change densities, which change potential ...
- A linear system is build with implicit drifts
 - Matrix element A_{ij} contains the effect of j-cell potential into i-cell density ($A_{ij} = \partial n_i / \partial \Phi_j$).



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Mesh geometry

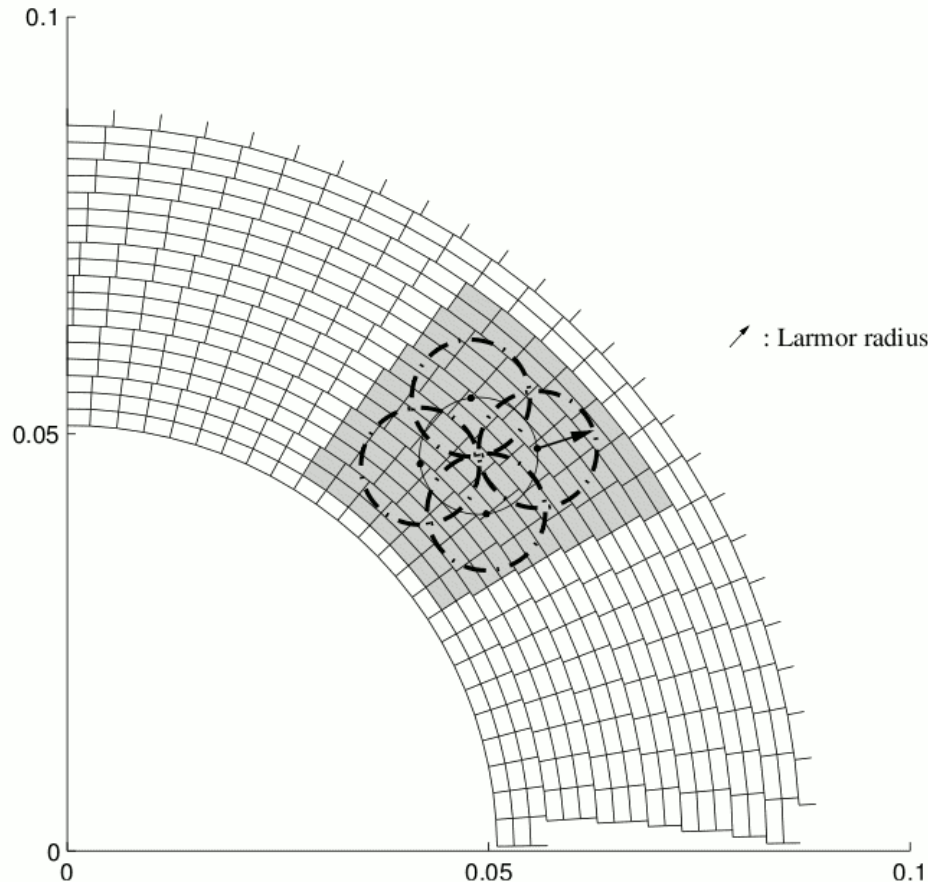


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Matrix coefficients from polarization



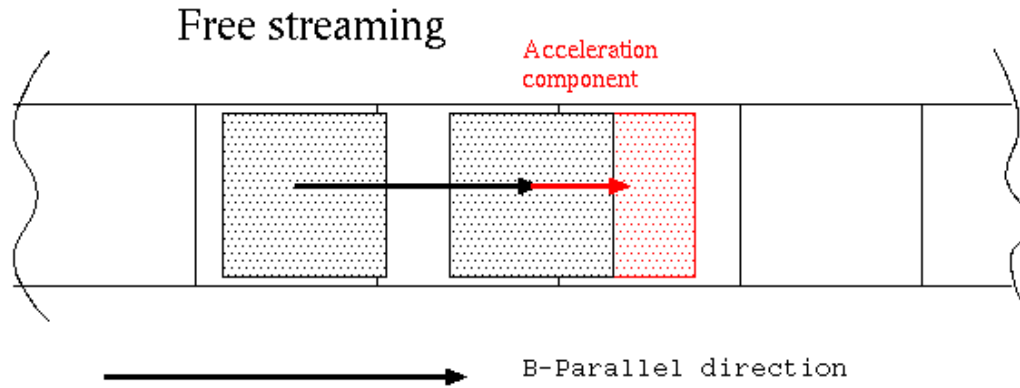
When particles spin around B-field, they cross several cells surrounding the gyrocenter



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Electron parallel treatment

$$\Delta x_{fs} = v \cdot \Delta t \quad \Delta x_a = \frac{1}{2} a \Delta t^2 = \frac{qE_{\parallel}}{2m} \cdot \Delta t^2$$



A.B Langdon et al (1983)

- E field in Δx_a is calculated at advanced time but at the position after free streaming
 - We demand that $|\Delta x_{fs}| \gg |\Delta x_a|$. It constrains Δt

$$\Delta t \ll \frac{\sqrt{8m_e kT}}{e |E_{\parallel}|} \quad \left\{ \begin{array}{l} kT = 100 \text{ eV} \\ E_{\parallel} = 50 \text{ V/m} \end{array} \right. \Rightarrow \Delta t \ll 1 \mu\text{s}$$



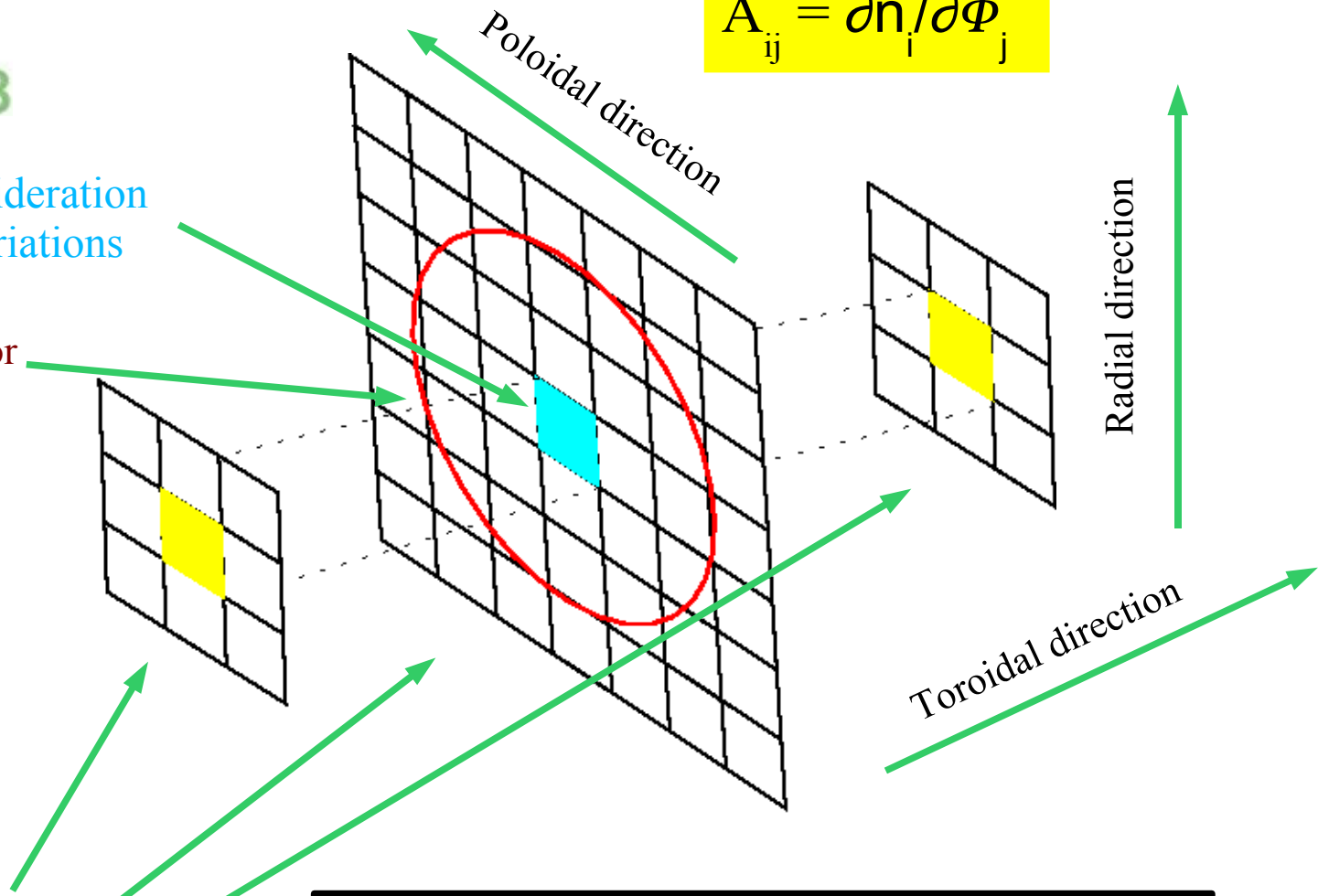
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Overall matrix coefficients

$$A_{ij} = \partial n_i / \partial \Phi_j$$

i-cell under consideration
suffer density variations

Larmor radius for
calculation of
gyroaverages



j-cells whose potential produce
variations of i-cell density

And this for every single cell in
the system in every processor.



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Memory usage

- The storage of matrix coefficients in those boxes takes most memory of the system, posing a real limit.
 - The boxsizes are equal for all cells while Larmor radius is not.
 - Matrix is not distributed across processors. Poor memory scalability.
- Typical memory requirements for real case:
 - $\text{ncell}=2 \times 10^5$, $\text{boxsize}=500 \rightarrow 800 \text{ MB}$. Unacceptable!!



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Domain decomposition

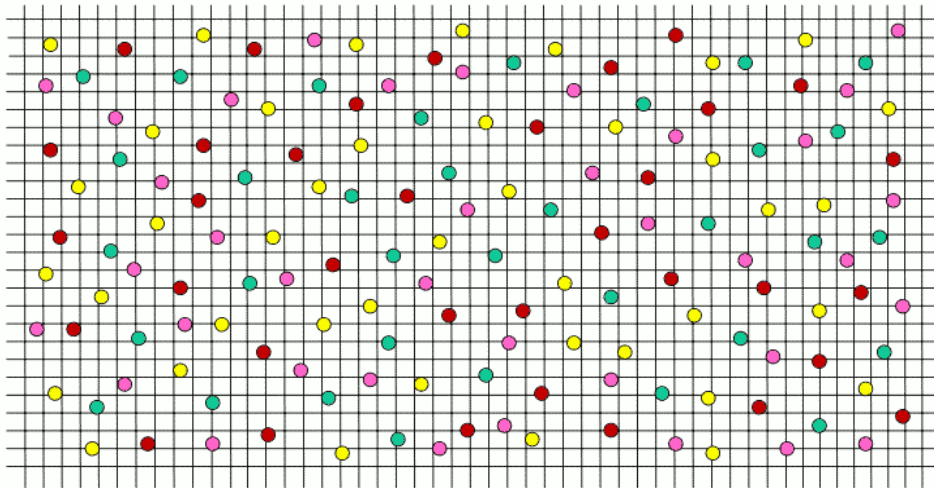
- Key question for DD: to what matrix coefficients is a given particle contributing?
 - Polarization calculations are contained in its Z-plane, both density variations (i-cells) and potentials (j-cells).
 - Electron parallel movement includes also neighbouring toroidal planes (both i- and j-cells), around particle.
- At last a certain particle only affects its toroidal plane and locally the neighbouring ones.
 - If we keep process particles inside a toroidal domain, their coefficients will NOT span the whole torus.



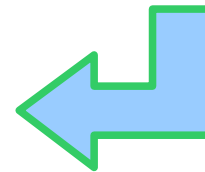
Particle distribution

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Processor 0 Processor 1 Processor 2 Processor 3

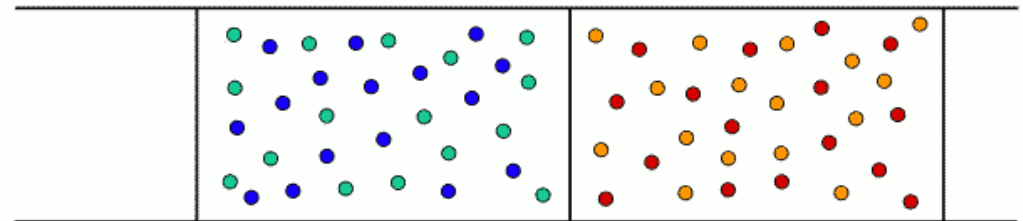


Original particle distribution



Processor 0
Processor 1

Processor 2
Processor 3



Distribution under toroidal domain decomposition

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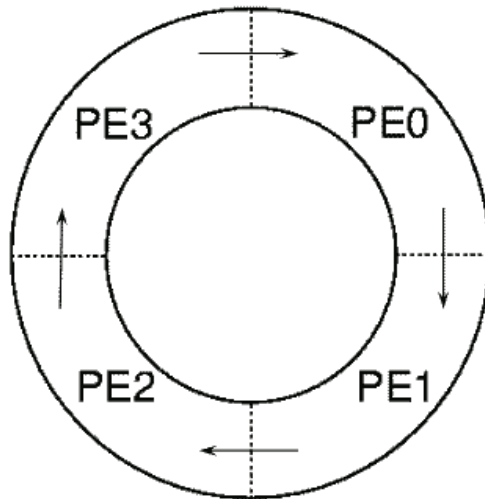


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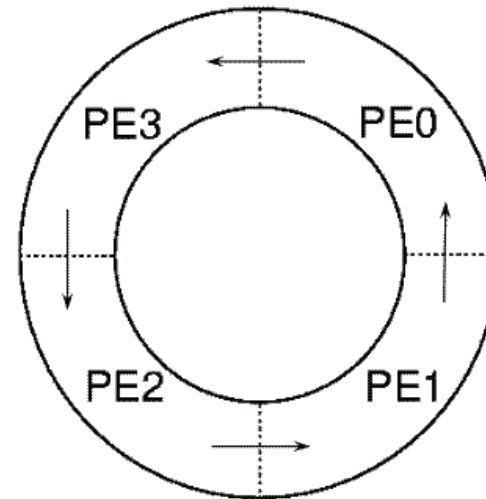
Particle transfer

- Particles have to be transferred to the proper domain every time they cross toroidal domain boundaries.
 - Simultaneous transfer (`MPI_SENDRECV`) in few steps.
 - Particle number per processor is bounded in practice.

STEP 1



STEP 2

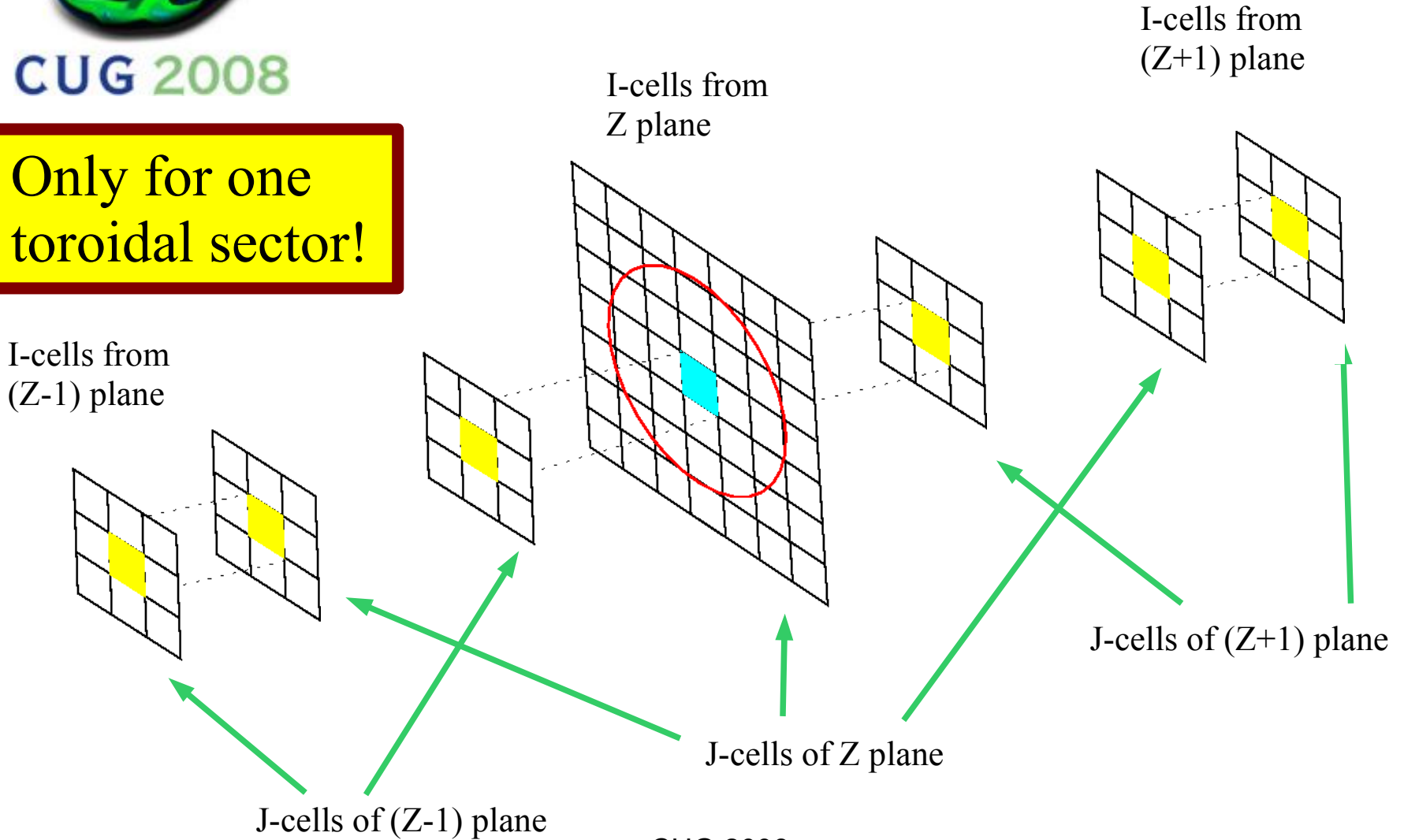




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Only for one toroidal sector!

Coefficients in memory



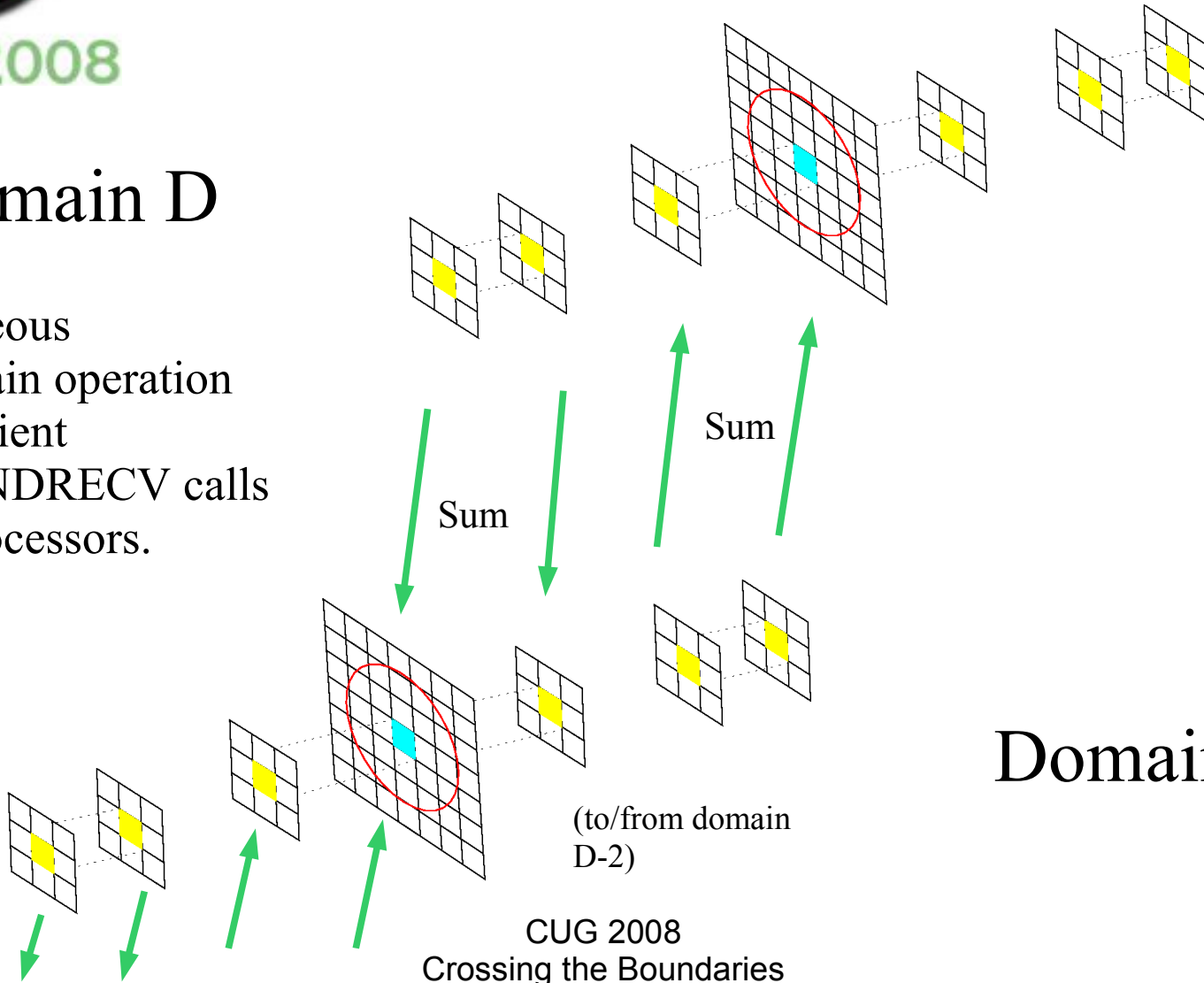


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Combining the whole matrix

Domain D

Simultaneous interdomain operation with efficient MPI_SENDRECV calls for all processors.



Domain D-1

(to/from domain D-2)



MPI Process topology

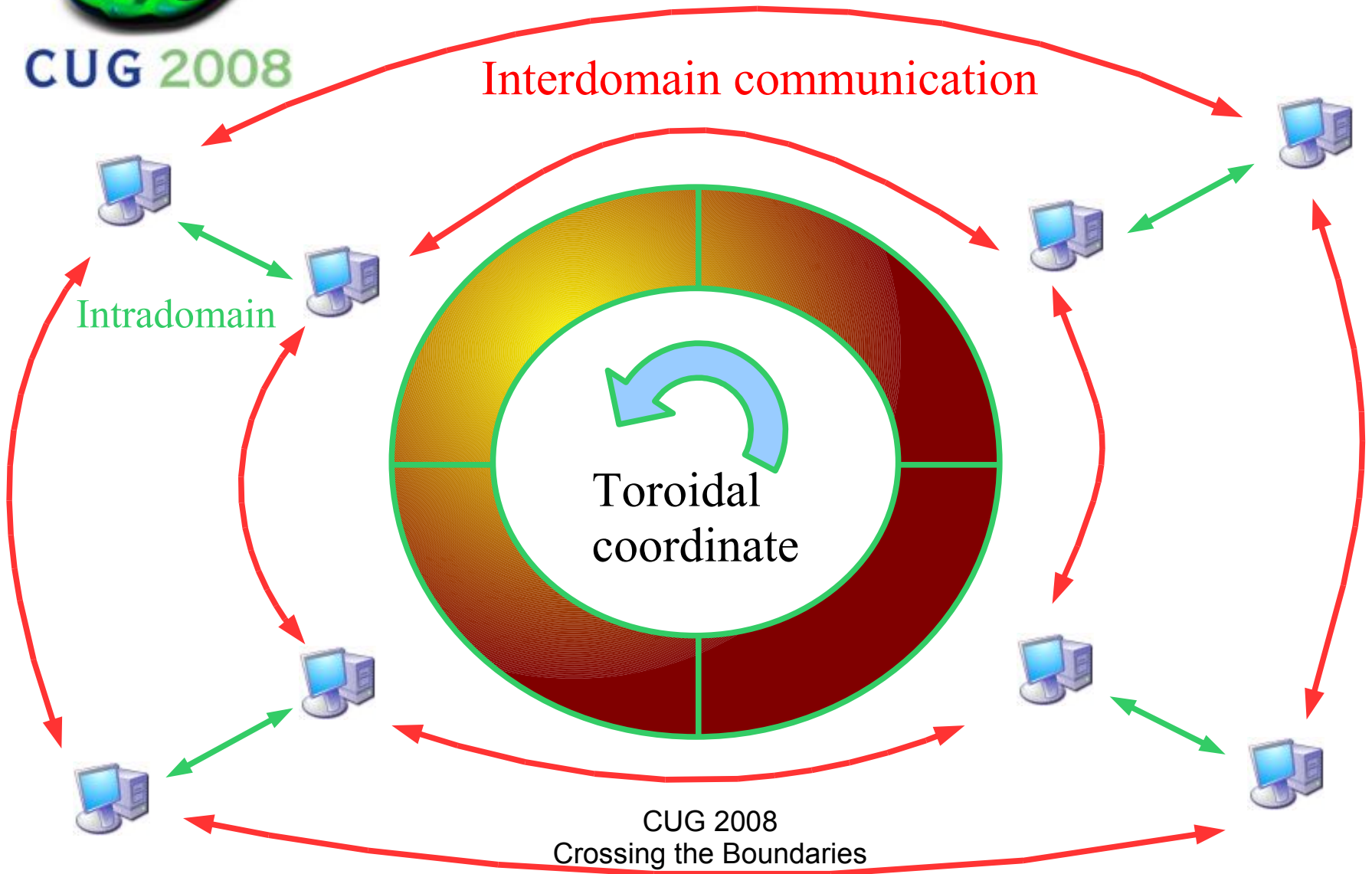
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Interdomain communication

Intradomain

Toroidal
coordinate

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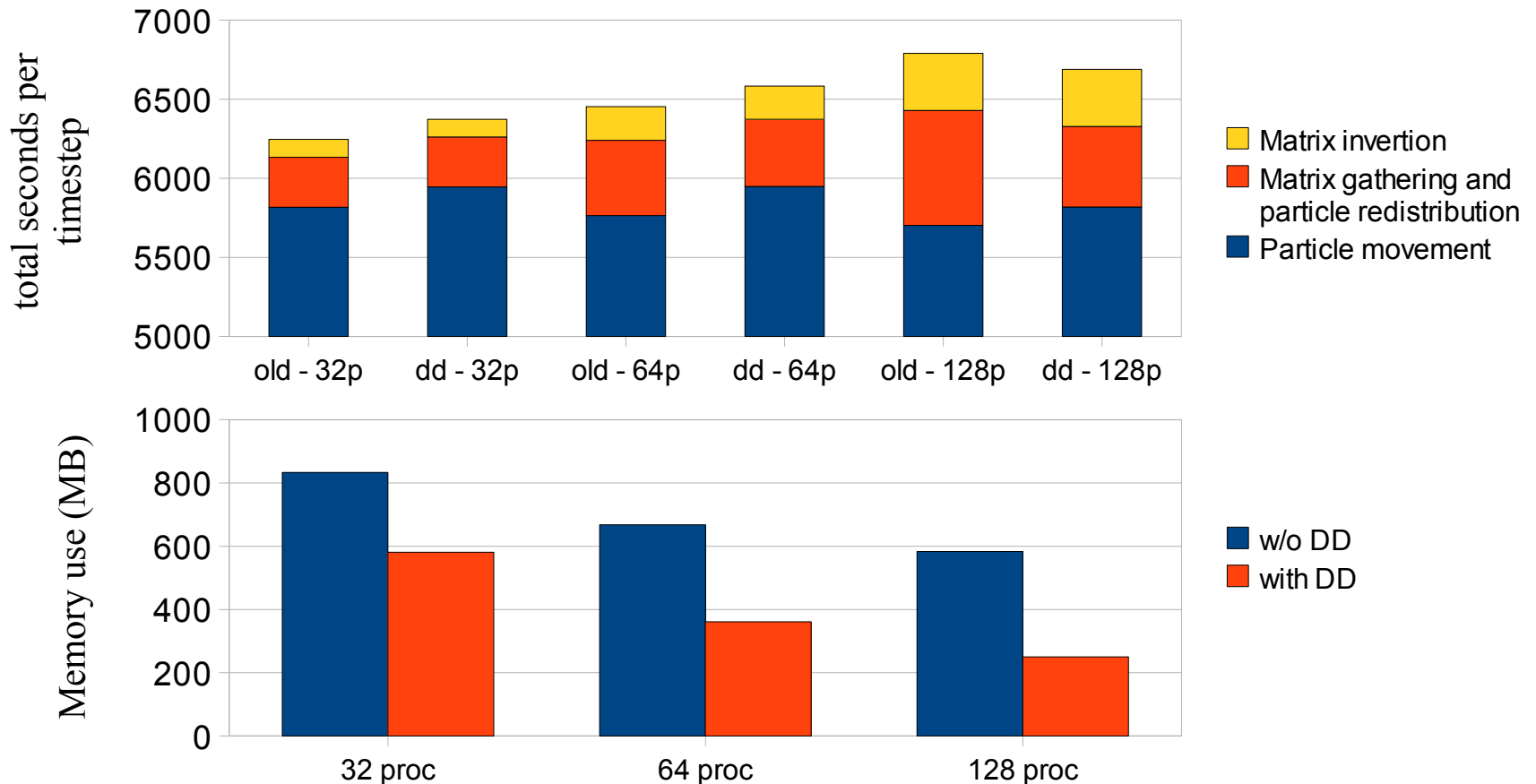
Performance results

- Test runs were performed on louhi with a variety of processor number.
- A case was selected with reasonable and favourable parameters
 - High cell number → most memory taken by matrix
 - Fine toroidal division → more domains



Results: computation time and max memory use

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Conclusions

- A domain decomposition algorithm has been developed and implemented into ELMFIRE
- Memory consumption has been strongly reduced, extending the code capabilities.
 - Specially true in low node memory systems like new supercomputers (Cray XT4, Blue Gene...)
 - Computation speed is not affected.
- Algorithm is transparent to matrix inversion.



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Acknowledgements

- Thanks to all members of the project and their institutions.
 - VTT leading the project
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 - UNED supporting my secondment
- Special thanks to the supporting institutions.
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