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# The Dynamic PBS Scheduler

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# Computing Environment

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- **Cray X1**
  - 2 Chassis, 128 MSPs, 1TB memory



- **Linux Clusters**
  - Over 1700 compute nodes

- **Panasas Storage**
  - Primary storage for cluster, secondary for Cray X1



# Why use a Dynamic PBS Scheduler?

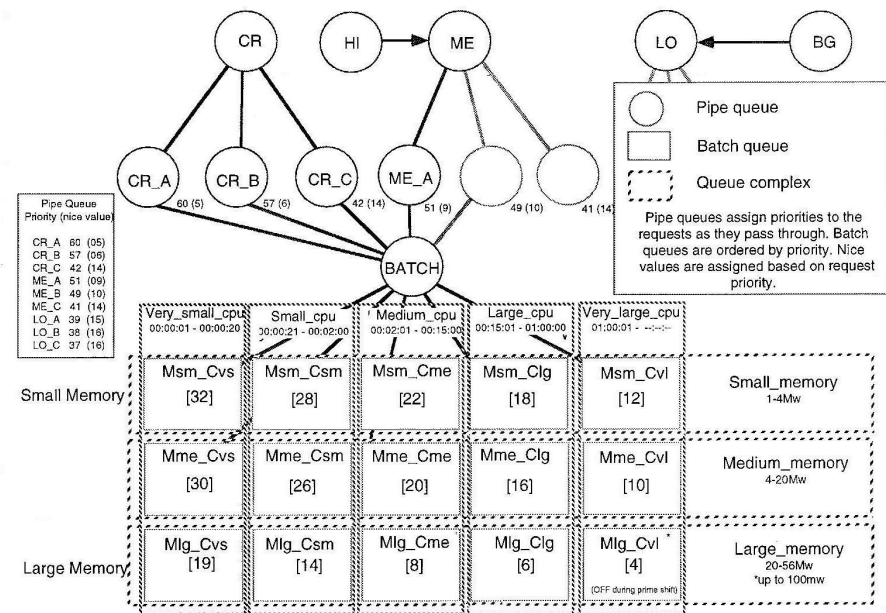
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- **Didn't want to write a complete scheduler from scratch**
- **Default PBS scheduler has a lot of functionality**
  - **Ordering by priority**
  - **User limits, queue limits, server limits**
  - **Starving jobs logic**
  - **Interaction with Cray's psched**
- **Multiple queues are useful...**
  - **Separate queues allow finer control of usage**
  - **Primary method for separating different "kinds" of jobs**
    - Short versus long
    - Varying memory or CPU requirements
- **...but problematic**
  - **User turnaround can suffer when a restricted queue gets swamped**
  - **Fixed queue limits can lead to underutilization...**
- **Many tuning options are not available with a single queue**
- **We needed a mechanism to balance queue limits based on a changing workload**

# History

- **First dynamic scheduler at Boeing was written in “C” and targeted to controlling NQS on our Cray T90’s**
- **A more limited dynamic scheduler was used on our SGI Origin 3800, written in Perl**
- **Current dynamic PBS scheduler (dyn\_pbs) is written in Perl**
- **dyn\_pbs is conceptually and functionally similar to T90 version**

Triton NQS Queue Configuration



# Goals

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- **Functionality**
  - Provide reasonable turnaround for all job classes
  - Honor user priorities
  - Minimize whitespace
  - Meet broad throughput targets
- **Simplicity**
  - Modest development effort
  - Easy to adjust and tune
- **Safety**
  - “Safe”
    - Does the minimum necessary
    - Can be run as an ordinary user (with PBS operator privileges)
    - Won’t put the system in a bad state
  - “Fail-safe”
    - Won’t leave the system unusable in case of daemon failure
    - Simple auto-restart via cron

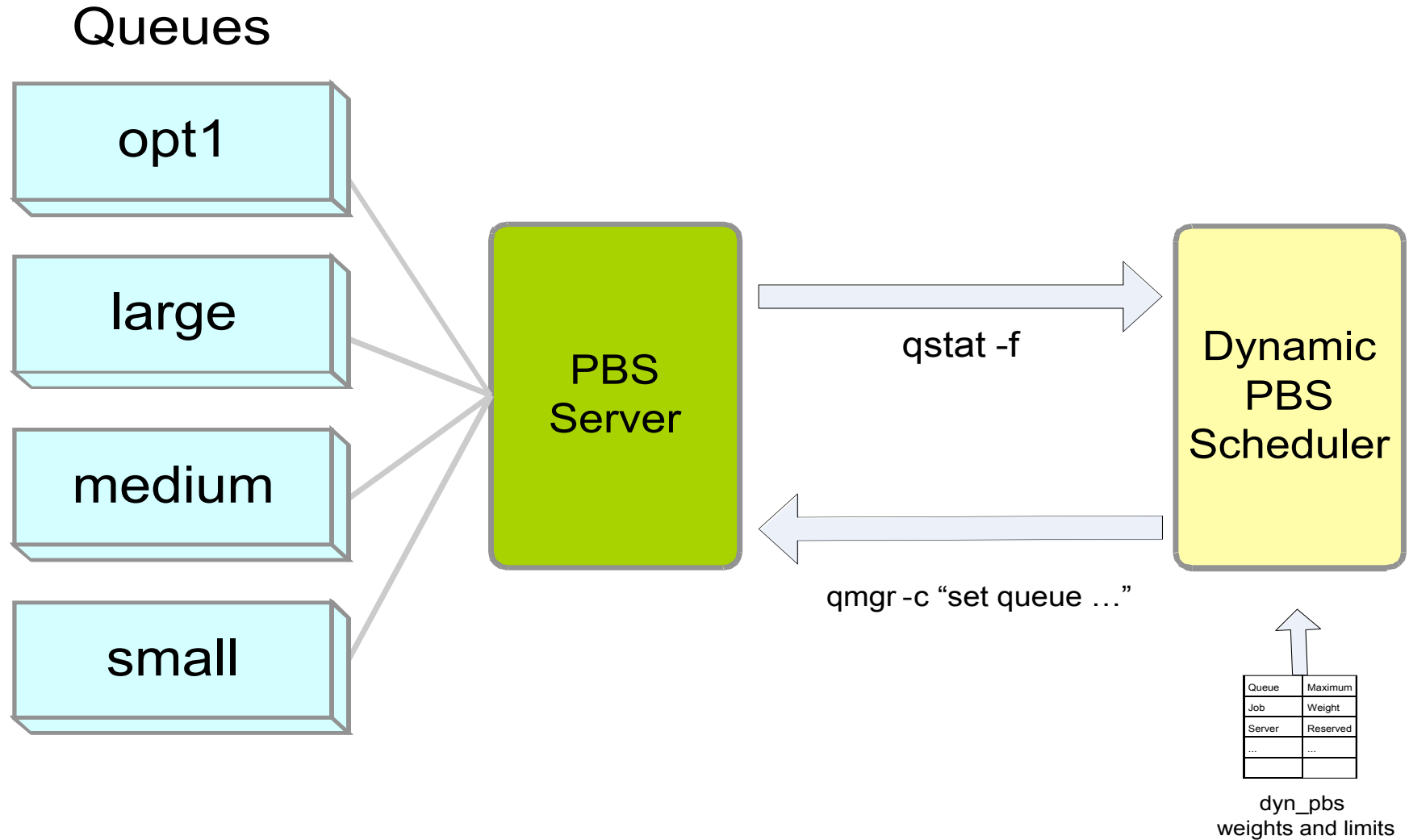
# Workload Characteristics

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- **Mix of very large and very small jobs**
  - Large jobs are long-running and consume significant percentage of MSPs (10%-20% each)
  - Smallest jobs are very short running and require a single MSP or SSP
  - Small jobs very sensitive to turnaround
- **Job Types:**
  - Optimization jobs using Overflow
    - Usually 16 MSPs, multiple cycles
  - Individual Overflow analysis case
    - 8-16 MSPs, single cases
  - TRANAIR analysis cases
    - Single MSP, usually multiple runs
  - ATLAS cases
    - Single MSP or SSP, short running

# Queue Structure and dyn\_pbs Daemon

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# Overview of dyn\_pbs Weights and Limits

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- **Server-related weights and limits**
  - **Server oversubscription factor**
  - **Reserved MSPs**
- **Queue-related weights and limits**
  - **Minimum, default, maximum number of MSPs**
  - **Queue weighting factor (for queued jobs)**
  - **Queue additional MSP weight per running job**
  - **Queue maximum weight**
  - **Queue oversubscription factor**
  - **Queue oversubscription order**
- **Job-priority-related weights**
  - **Priority-based MSP weighting factor**
  - **Priority-based job weight**



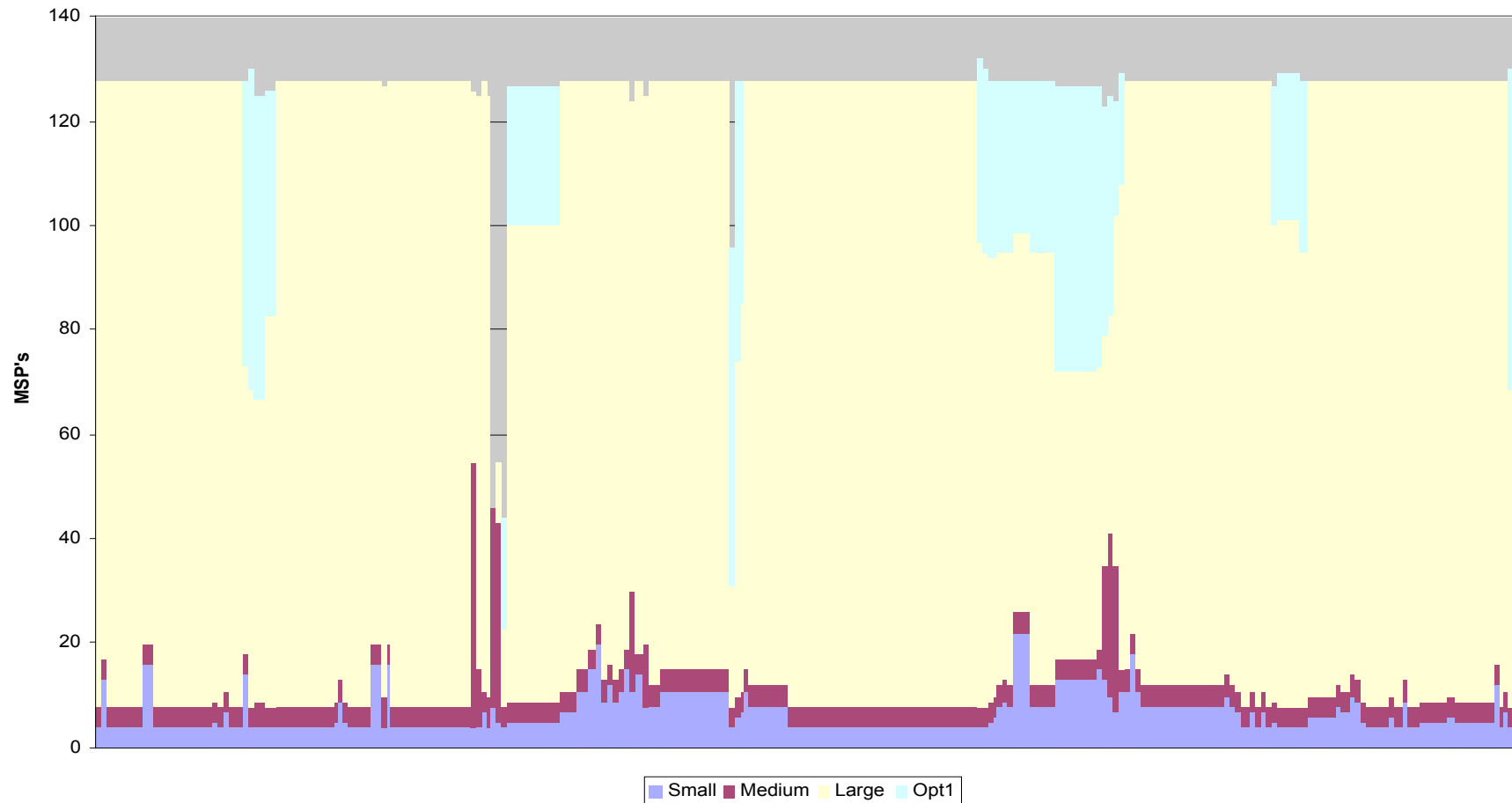
# Overview of dyn\_pbs Process

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- **Determine # of MSPs**
- **Gather data from PBS (qstat -f)**
- **Compute each job's weight**
- **Compute initial queue MSP distribution**
- **Reclaim MSPs from any queues above their maximum**
- **Allocate reclaimed MSPs to other queues**
  - Proportional to their computed limit
- **Deal with oversubscribed queues**
  - Subtract MSPs from all queues, based on queue oversubscription factors
- **Issue “qmgr” directives to adjust queue's MSP limits**
  - Only for queues who's limits have changed
- **Delay, then repeat...**

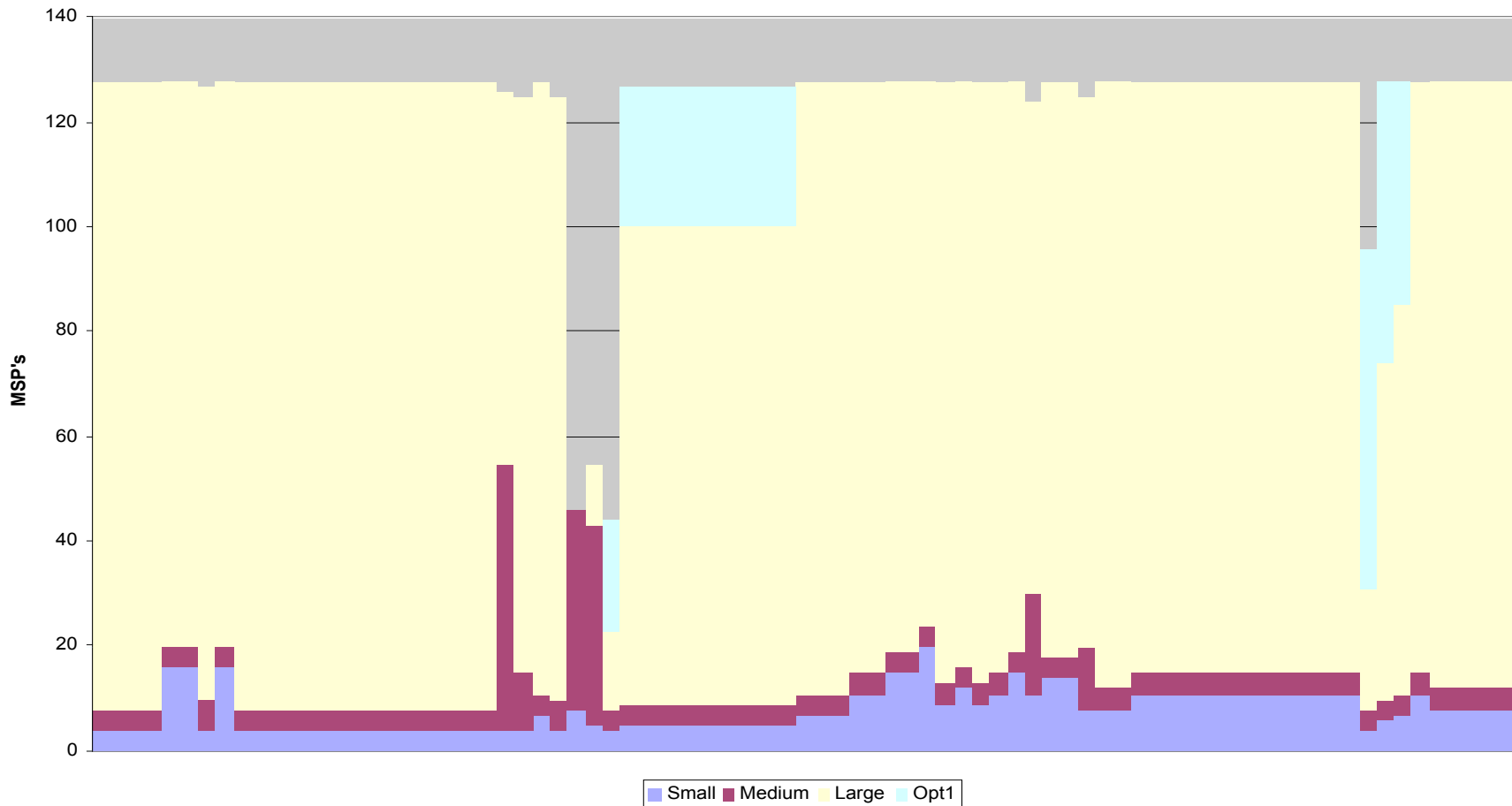
# Dynamic Queue Limit Adjustments

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# Dynamic Queue Limit Adjustments - Detail

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# Results

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- **“No phone calls...”**



# Understanding Turnaround

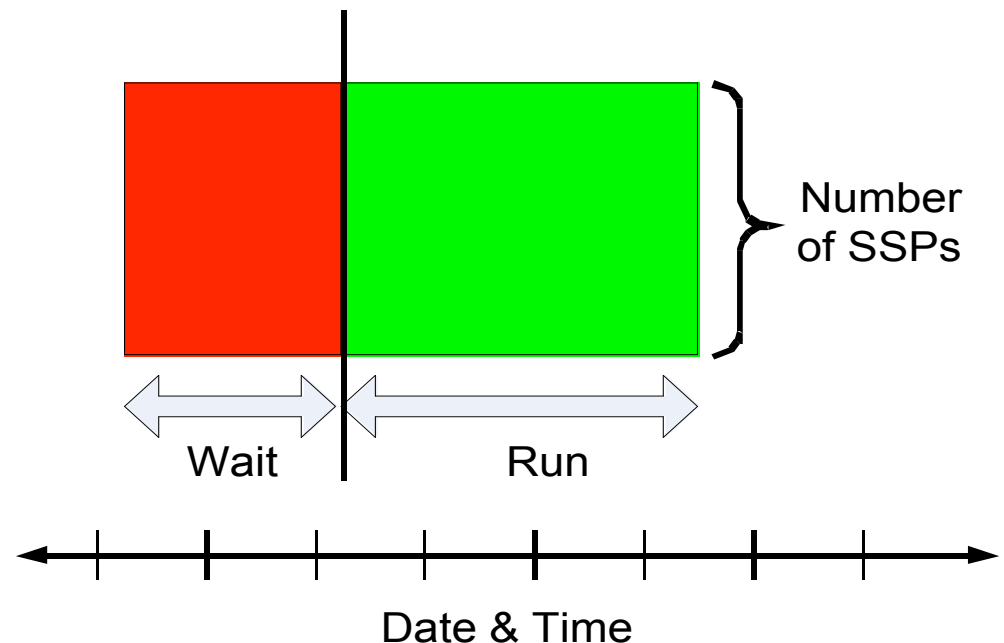
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- **The two primary goals of dyn\_pbs were maximizing utilization and minimizing turnaround time**
  - Measuring overall system utilization is easy
  - Turnaround measurements are more problematic
- **Tried several metrics**
  - Average wait time, average ratio of wait to run times
  - Percentiles for wait time or ratios
  - Same metrics bucketed or weighted by job size
- **No single summary metric really told us what was going on**
- **In measuring turnaround, outliers are often important**
  - But summary statistics couldn't answer *why* these jobs were outliers
- **“Wouldn't it be nice” if we could get a birds-eye view of the details...**

# The “Red/Green” Turnaround Charts

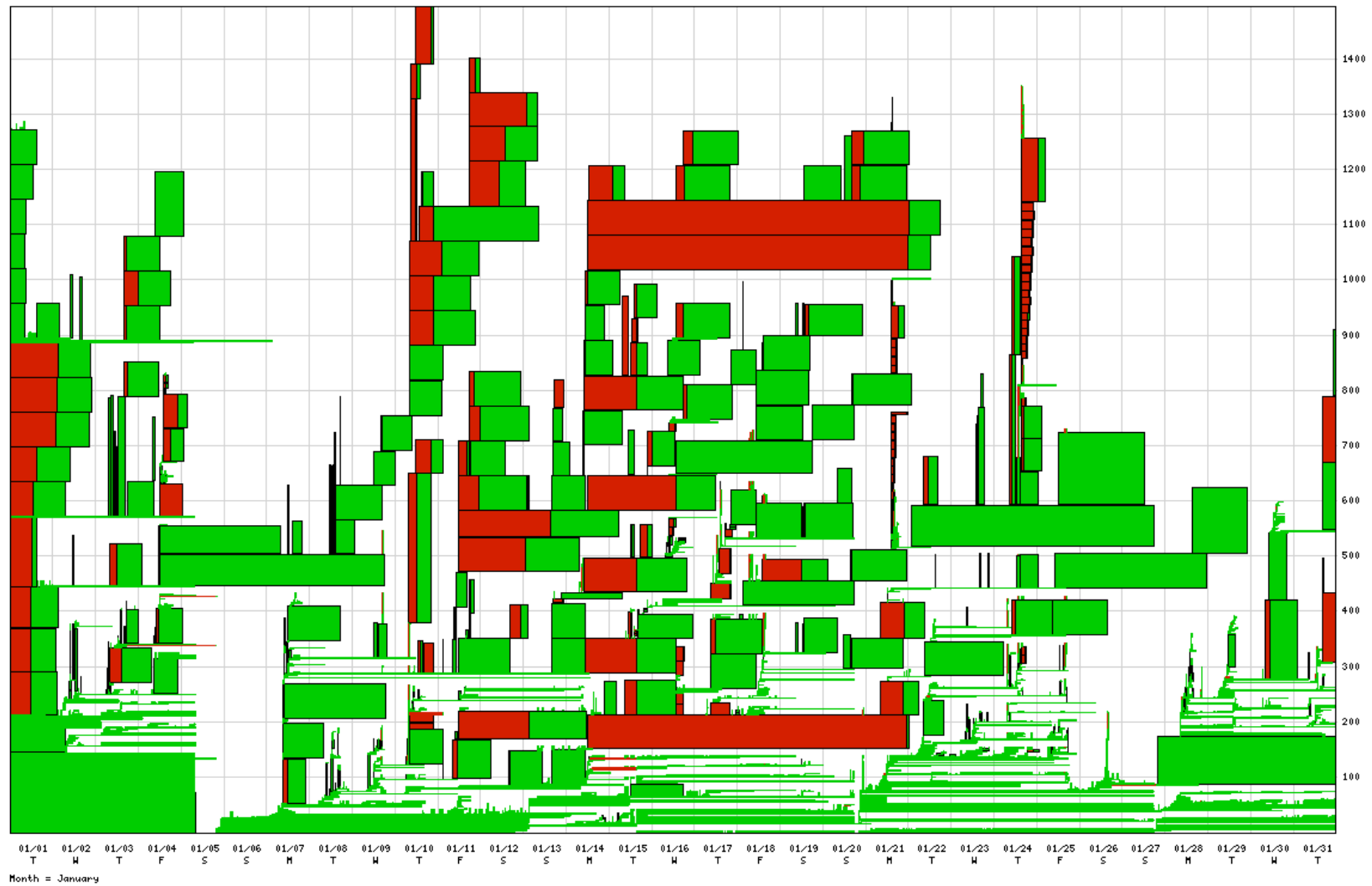
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- Each job is represented by a two-color rectangle
  - Red indicates wait time (queued)
  - Green indicates execution time
- Height of rectangles represents number of **SSPs** (or nodes)
- Horizontal axis is a timeline
- Vertical position of jobs is not significant (first-fit)



# Turnaround - Wait versus Run

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# Summary and Conclusions

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- **Varying workloads are common on many systems**
- **The default PBS scheduler has a large number of useful features, but does not adjust limits dynamically**
- **Multiple queues with fixed limits can result in**
  - **Failure to meet turnaround expectations**
  - **Increased whitespace (idle capacity)**
- **Adding a modest dynamic component to a fixed queue structure can improve utilization and still meet user expectations**
- **The dynamic PBS scheduler has helped us better utilize our Cray X1**



