Molecular Modelling and the Cray XC30 Performance Counters

Michael Bareford, ARCHER CSE Team michael.bareford@epcc.ed.ac.uk





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Introducing ARCHER

Advanced Research Computing High End Resource











www.archer.ac.uk





Introducing ARCHER

Cray XC30 MPP, 4920 Compute Nodes Dual Intel Xeon processors (Ivy Bridge), 24 cores, 64 GB

Dragonfly topology

rank 1: intra-chassis, sixteen 4-node blades (Aries interconnect) rank 2: intra-group (two cabinets per group) rank 3: optical, inter-group (13 groups make up ARCHER)

Tests conducted on 2-cabinet Test Development Server

Private to EPCC, minimises resource contention.

ARCHER supports three programming environments Cray (v8.3.7), Intel (v14.0.4) and gnu (v4.9.2) running on CLE v5.1 OS





Cray XC30 Power Management Counters

Supported counters obtained by running papi_native_avail on compute node.

Running Average Power Limit Counters	Power Management Counters
PACKAGE_ENERGY (nJ)	PM_POWER:NODE (W)
DRAM_ENERGY (nJ)	PM_ENERGY:NODE (J)
PP0_ENERGY (nJ)	PM_FRESHNESS

PACKAGE = processor (two sets of RAPL counters per node) RAPL instantaneous, PM energy cumulative





PM Library

(https://cug.org/proceedings/cug2014_proceedings/includes/files/pap136.pdf)

Hart et al. [3] have provided a library that allows one to monitor the PM counters directly

(/sys/cray/pm_counters)

Counter files updated every 100 ms.

Measurements cover CPU, memory and any other hardware contained on the processor daughter card.

Consumption due to the Aries network controllers and beyond is excluded however.





PM MPI Library (https://github.com/cresta-eu/pm mpi lib)

Only one MPI process per node must read the PM counter file on that node.

Only one MPI process (e.g., rank 0) should collate the data, writing it to a single file.

```
CALL pm_mpi_open(out_fn)
DO i=1,nstep
...
CALL pm_mpi_monitor(i,1)
...
CALL pm_mpi_monitor(i,2)
...
ENDDO
CALL pm mpi close()
```

Minimal but flexible instrumentation.





pm_mpi_open(char* out_fn)

Call MPI get processor name to determine unique number of the node on which calling process is running.

Do MPI **comm split** on the node number, then MPI **all reduce** to determine process that has lowest rank on each node – this is the monitoring process.

The monitoring processes open their respective PM counter files.

All monitoring processes create another sub-communicator, one that unites them all, thus rank 0 can determine the number nodes in use.





pm_mpi_monitor(int nstep, int sstep)

Monitoring processes only read the counter files.

Subsequent MPI **all reduce** sums energy and power counters over all nodes.

Rank 0 writes counter data to output file.

Non-monitoring processes wait at MPI barrier.







Monitoring processes close PM counter files.

Rank 0 also closes performance output file.





Molecular Modelling Code I

DL_POLY v4.05 (MPI) https://www.stfc.ac.uk/SCD/44516.aspx



Test case 40 (ionic liquid dimethylimidazolium chloride) over four nodes (96 cores).

CONTROL steps = 20 000 Instrument main loop, ./vv/w_md_v.f90

Perform six runs for each compiler environment.





Energy use per model time step (cray)



Every thousand iterations, DL_POLY restart files are written to disk – energy use increases by 16 times.





Energy use per model time step (gnu)







Energy use per model time step (intel)



Increase now \approx 95 times!







Overall results

Six runs performed for each compiler environment.

Cray: 1.92 ± 0.02 MJ over 1748 ± 2.6s

Intel: 1.97 ± 0.01MJ over 1770 ± 2.7s

gnu: 2 ± 0.02 MJ over 1823 ± 2 s





Time use per model time step (compute iterations)



Majority of steps run faster for Intel Compared to Cray (and gnu).







Time use per model time step (snapshot iterations)



Snapshot iterations take significantly longer.

If the Intel snapshot iterations had runtimes comparable to the Cray and gnu results, the Intel compiled-code could be the most energy efficient.





Point-in-time Power Distributions



Distributions from all 18 simulations.

Intel runs draw slightly (~2%) more power.







Molecular Modelling Code II

CP2K v2.6.14482 (MPI/OpenMP) http://www.cp2k.org



GNU programming environment only ./tests/QS/benchmark/H2O-1024.inp over eight nodes (192 cores)

MOTION.MD.STEPS = 100

./src/motion/md_run.F, qs_mol_dyn_low()
Real MD Loop





Cumulative energies and run times for different OpenMP threading options

aprun options	Energy (MJ)	Run Time (hr)
-n 192 -N 24 -S 12 -d 1	52.263	5.4
-n 96 -N 12 -S 6 -d 2	49.727	5.94
-n 64 -N 8 -S 4 -d 3	45.052	5.27
-n 48 -N 6 -S 3 -d 4	48.819	6.26
-n 32 -N 4 -S 2 -d 6	54.284	7.47
-n 24 -N 3 -d 8	71.54	11.57
-n16 -N 2 -S 1 -d 12	91.342	16.72





Energy usage against run time for different OpenMP threading options







Normal distributions and CDFs inferred from point-in-time power histograms



In general, power deviation increases with thread count.





CrayPat Alternative (perftools module)

Instead accessing PM counter files directly it is possible to use CrayPat API calls.

```
CALL PAT_region_begin(id, label, istat)
IF (monitoring process) THEN
   CALL PAT_record(PAT_STATE_ON)
ELSE
   CALL PAT_record(PAT_STATE_OFF)
ENDIF
DO i=1,nstep
   ...
IF (monitoring process) THEN
      CALL PAT_counters(PAT_CTRS_PM, names, values)
   ENDIF
   ...
ENDDO
CALL PAT region end(id)
```

Must load **perftools** module before compilation, then instrument exe with **pat_build -w** command.

Need to set **PAT_RT_PERFCTR** environment variable in job submission script. Also tied to a particular counter category.





PAT MPI Library

(https://github.com/cresta-eu/pat_mpi_lib, coming soon)

pat_mpi_open(char* out_fn)

Monitoring processes turn PAT recording on.

And call PAT_counters(cat[i],0,0,&nc) for each counter category specified by MY_RT_CTRCAT environment variable. Allocate memory required to hold counters.

pat_mpi_monitor(int nstep, int sstep)

Call PAT_counters(cat[i],&name[j],&val[j],&nc) for each counter category specified by MY_RT_CTRCAT, where the actual counter names are given by PAT_RT_PERFCTR.





Example Job Script

```
...
module load perftools
...
export PAT_RT_SUMMARY = 1
export MY_RT_CTRCAT = PAT_CTRS_RAPL, PAT_CTRS_PM
export PAT_RT_PERFCTR = PACKAGE_ENERGY, PP0_ENERGY, DRAM_ENERGY,
PM_POWER:NODE, PM_ENERGY:NODE
```

aprun -n 96 ./DL_POLY.z+pat >& stdouterr





PM files vs PAT API

Average DL_POLY power consumption and runtimes for six runs per compiler environment.

	PAT API	PM Files
Cray	1.96 MJ (1747 s)	1.92 MJ (1748 s)
Intel	1.99 MJ (1762 s)	1.97 MJ (1770 s)
gnu	2 MJ (1819 s)	2 MJ (1823 s)

Higher Cray energy due to different node assignment.





PAT API Comparison







PAT API DRAM Energy (Cray 1/6)







PAT API DRAM Energy (Intel 4/6)



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Conclusions I

DL POLY results show the expected correlation between energy use and runtime.

Cray-compiled code uses the least energy, followed by Intel then gnu. Although differences are slight.

Closer examination of the data, reveals that the Intel runs *might* use the least energy, if the compiler options could be set such that the Intel snapshot iterations had runtimes comparable with the Cray and gnu results.





Conclusions II

Energy use will depend on the number of threads per MPI process: using multiple threads can reduce runtimes and energy usage but not beyond a certain thread count.

Three threads is the **optimum thread count** for CP2K running over eight nodes with the H2O-1024.inp data set.

Further work could investigate the importance of node assignment within the ARCHER dragonfly topology as regards energy consumption.





Further work (CP2K)

Running with three threads per MPI process, one could compare energy usages for the following scenarios.

- 1) All eight nodes from the **same chassis**.
- 2) Four nodes from one chassis and four nodes from a **different chassis**.
- 3) Same as scenario two but involving a chassis from a **different group**.

The usefulness of this work would be in understanding the energy cost of communicating via the rank 2 and/or rank 3 networks.



