CUG 2015 Technical Talk: Applications

# MP-sort: Sorting at Scale on BlueWaters in BlueTides Simulation

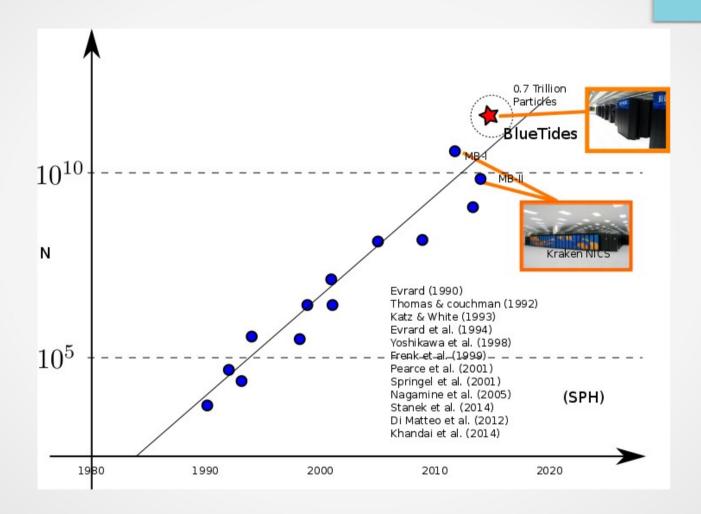
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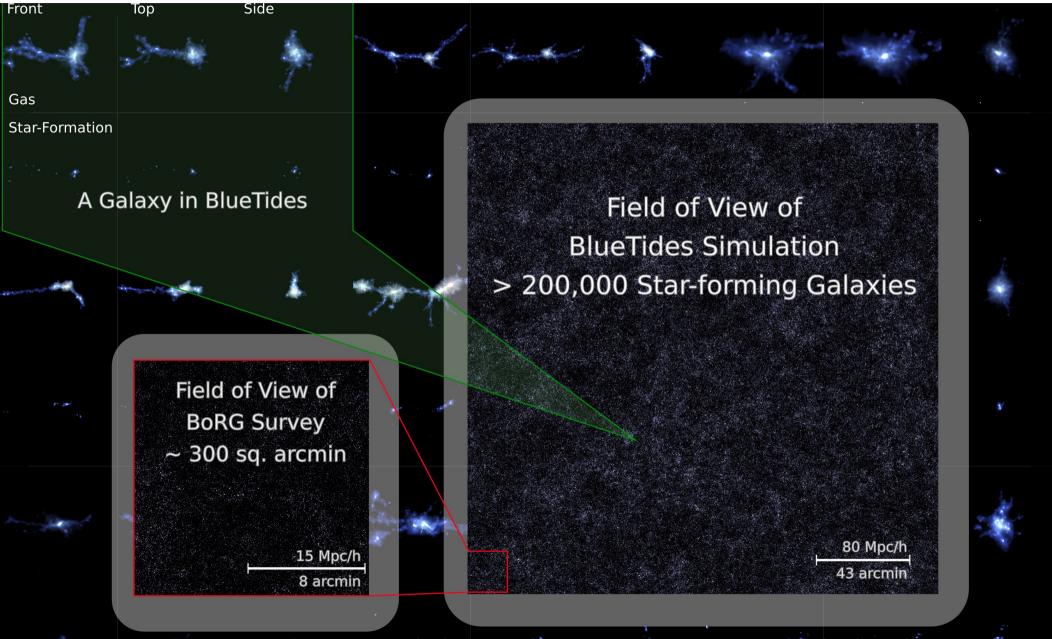
### **BlueTides Simulation**

- Largest hydro-dynamical simulation of the universe;
- 700 Billion Particles;
- 20250 of Cray XE nodes in BlueWaters; (90% utilization)
- 81000 MPI ranks, 8 OpenMP Threads each;
- MP-Gadget:
  - Substantially improved scaling for BlueTides

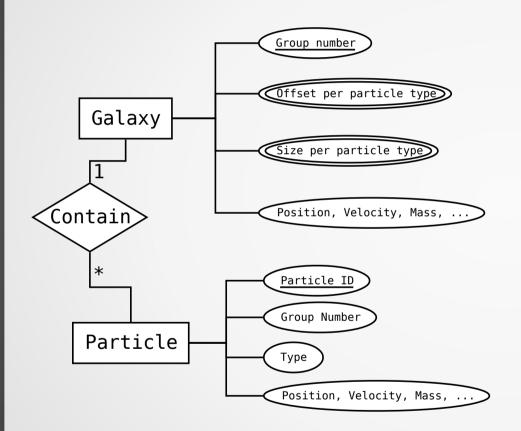
### BlueTides on the Chart



# BlueTides: How did first galaxies rise from a uniform universe?

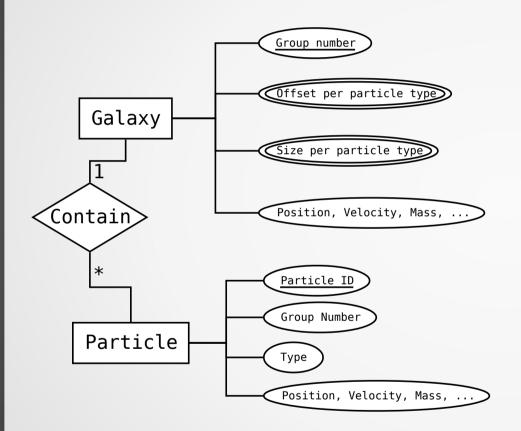


# **Galaxy Catalog**



- A physicist's database:
  - **Sort** particles by their Group Number
  - Store a jump-table for the offset of the first particle in a galaxy
  - More complicated in reality, because particles have different types
  - Google: bigfile github

# **Galaxy Catalog**



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#### Introducing MP-sort

- At BlueTides scale (81,000 ranks, choice of sorting algorithm matters.
  - Comparison based, parallel Merge-sort scales badly.
- MP-sort is the new sorting module in BlueTides Simulation
  - Partition-based sorting
  - Performs reasonably well
  - A standalone library
    - Simple API, via C and Python
    - Small code footprint ( < 2,000 lines)</li>
  - http://github.com/rainwoodman/MP-sort

### **MP-Sort: Partition-Based Sorting**

Many names:

Partition-sort, histogram-sort, bucket-sort;

- Distributed data
- Naive algorithms
- "Plan & Deliver"
- Need numerical keys for items
  - galaxy number

- Algorithm
  - 1. Local Sorting
  - 2. Find Splitters: edges of the histogram bins;
  - 3. Solve for Shuffling Matrix (P x P);
  - 4. Shuffle Items: moving from initial ranks to the final ranks
  - 5. Local Sorting

#### Partition-Based Sorting Illustrated

[8 6 4 2 0] [9 7 4 3 1] 1. Local Sorting [0 2 4 6 8] [1 3 4 7 9] 2. Find Splitters (0, 4, 10)3. Calculating Shuffling Matrix [0 2 4 6 8] [1 3 4 7 9] 4. Shuffle with MPI Alltoallv  $[0\ 2\ 4\ 1\ 3]$   $[6\ 8\ 4\ 7\ 9]$ 5. Local Sorting  $[0\ 1\ 2\ 3\ 4]$   $[4\ 6\ 7\ 8\ 9]$ 

### Partition-based Sorting: Remarks

- Simplest Implementation
  - Local sorting: qsort\_r
  - Splitter finding: binary search
  - Shuffle: MPI\_Alltoallv
- Plan & Deliver:
  - Any item is on the network at most once.
- Only non-trivial step is to solve for Shuffling Matrix.

#### Step 3: Solving for Shuffling Matrix

#### (0, 4, 10) [0 2 4 6 8] [1 3 4 7 9]

- Shuffling Matrix L[q, p]:
  - SendDispl: Rank p sends items L[q 1, p] : L[q, p] to Rank q;
  - **Bounded** by  $C_1[q, p] \le L[q, p] \le C_2[q, p]$
  - **Constrained** by total number of items to be received per rank
- Lower and Upper Bounds:
  - $C_1[q, p]$  is the total number of items **less than** splitter E[q];
  - C<sub>2</sub>[q, p] is the total number of items less than or equal to splitter E[q].
  - $C_1 = [(0, 2, 5), (0, 2, 5)], C_2 = [(0, 3, 5), (0, 3, 5)]$

#### **Parallel Solver**

(0, 4, 10) [0 2 4 6 8] [1 3 4 7 9]

- For every column in L
  - Initialize with lower bound C<sub>1</sub>
  - Increase the items in L from lower to high row, limited by the upper bound C<sub>2</sub>
  - Until the column sum equals to the expected (cumulative) sum.
- Parallel in columns

$C_1 = [(0),$	2,	5),
(0,	2,	5)]
$C_2 = [(0),$	З,	5),
(0,	З,	5)]
L=[(0,	2,	5),
(0,	2,	5)]
<b>K</b> Sum of L: 0,	4,	10
L=[(0,	3,	5),
(0,	2,	5)]
/ Sum of L: 0,	5,	10

# Shuffling Matrix Solver: Remarks

- With parallelism:
  - Time complexity is O(P);
  - memory requirement per rank is O(P);
- Without parallelism both becomes O(P<sup>2</sup>)
  - 100,000 Ranks => 10G elements in Shuffling Matrix!
- Communication overhead is small
  - 3 AlltoAll communication to transpose  $C_1$ ,  $C_2$ , and L.
- Stable
  - Maintaining relative ordering of non-unique items
  - Items from lower ranks are sent to lower ranks

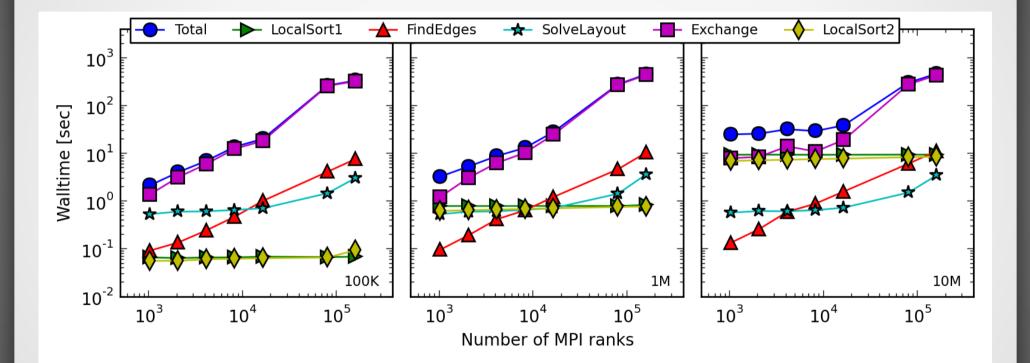
# **MP-Sort: Algorithm Summary**

- Intuitive algorithm:
  - Massively parallel sorting in 5 steps
- Standard routines:
  - qsort\_r, bindary search and MPI\_Alltoallv
- No local optimization was done
- "Plan & Deliver"
  - A single call to MPI\_Alltoallv
  - Items are on the network at most once
  - Optimal Communication

### Benchmarks

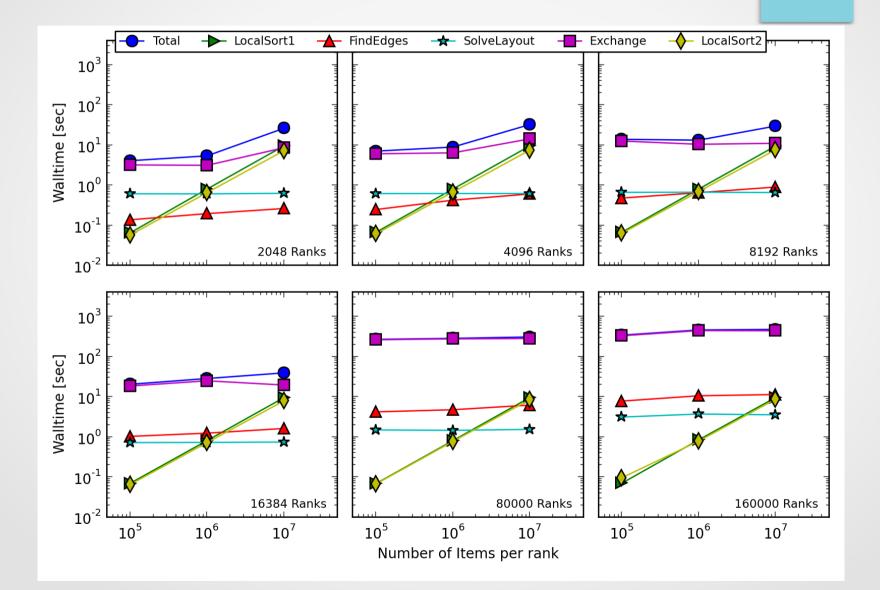
# How does MP-sort perform?

# Scaling with fixed load



Single call to MPI\_Alltoallv Optimal communication 99% of wall-time

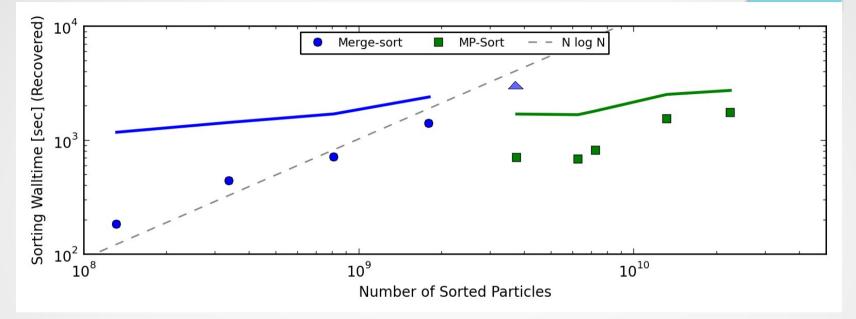
# Scaling with fixed ranks



## Insights from Benchmarks

- In large scale parallel applications (~100,000 MPI ranks)
  - Effectiveness of local optimization can be marginalized
  - Because, communication eventually takes over (99% of walltime)
- What does not help:
  - Overlapping communication with local sorting
  - Merge instead of sorting in final step
  - Requiring unique keys
- What really helps:
  - Faster inter-connection network, lower latency and higher bandwidth;
  - And maybe, a smarter MPI\_Alltoallv

# **Production in BlueTides**



- 10x faster than the old merge sort module
- Sorting is no longer the bottleneck
- ~ 2000 seconds per catalog
- ~ 20 catalogues produced, and actively used in scientific publications

# Further Insights

- MP-sort is a key part enabling the scientific discovery in BlueTides
- Building "relational" scientific simulation data
  - (somewhat) Big Data in a traditional HPC environment
  - Database perspective, without database management systems
  - Efficiently; as fast as the BlueWaters allows
- Parallel non-numerical algorithms alike have a place in large scale numerical applications

# Conclusion

- MP-sort: A Library for Massively Parallel Sorting
  - Optimal in communication
  - Performed at scale on BlueWaters for BlueTides simulation
  - Scaling Tests up to 160,000 cores
    - MPI\_Alltoallv is the key
  - A tool for Big Data analysis on traditional HPC infrastructure
- http://github.com/rainwoodman/MP-sort
  - C Interface
  - Python Interface
  - Like MP-sort on Github!

# Building the galaxy catalog

- 1. Assign global index to particles;
- 2. Sort global index of particles by galaxy/group number;
- 3. Assign ranks to particles
- 4. Sort ranks of particles by global index;
- 5. Exchange particles to the ranks with particle-exchange module

#### Sorting is used twice!

# Weak Scaling Summary

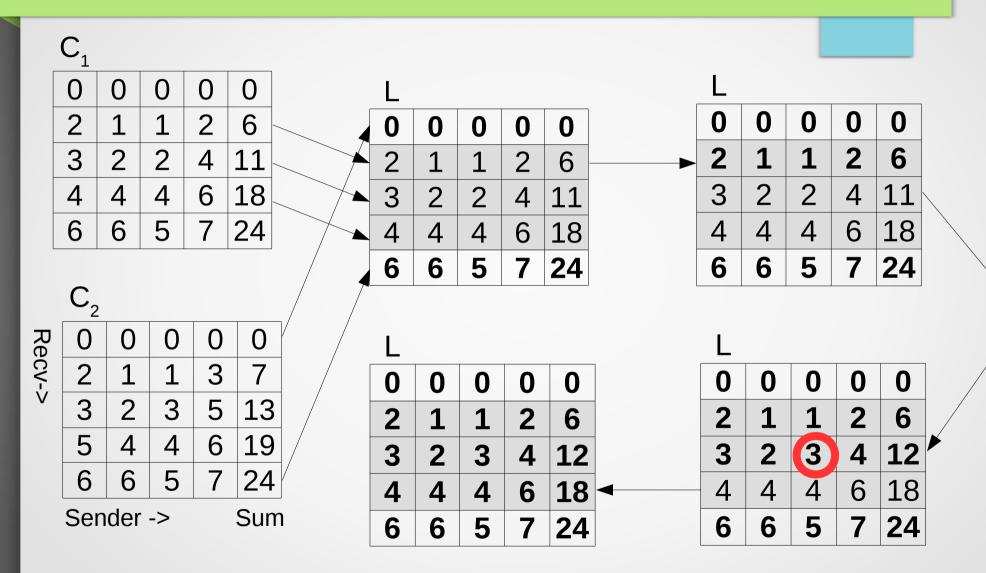
- At scale (large load and large number of ranks), communication dominates the total time
- Hardware and software implementation of MPI\_Alltoall seems to treat large number of ranks differently, as seen by the sudden jump at 80000 ranks.
- Matrix solver scales worse than linear:
  - A large fraction of time is in Alltoall of  $C_1$ ,  $C_2$  and L;
  - Still small fraction of time than the Alltoall of data items.
- Local sorting always a small fraction of wall-time.

#### Galaxy catalogue

- Galaxy catalog (PIG)
  - Less than 5% of all particles; or 1.5 TB in size;
  - Contains all galaxies;
  - Particles are indexed by galaxies;

- Full snapshot:
  - 40 TB per snapshot
  - Hard to transfer and analyze
  - challenging for offline analysis

#### Step 3: Parallel Solver Example



# Strong Scaling Summary

- Small number of ranks
  - The single AlltoAll operation uses a small fraction of walltime (~ 30%)
  - Increasing number of items increases walltime; due to increased Local sorting time
- Large number of ranks
  - The single AlltoAll operation uses a large fraction of walltime (~ 90%)
  - Increasing number of items does not increase walltime;
  - Walltime of local sorting is negligible;
  - Walltime of Split and Matrix solver is stable and negligible.